Rarely does a process use all its address range. In fact, many processes use only a small fraction of the address space available to them. It would be wasteful in these cases to create a page table with entries for every page in the address range. Most of this table would be unused but would take up valuable memory space. Some systems provide hardware, in the form of a **page-table length register (PTLR)**, to indicate the size of the page table. This value is checked against every logical address to verify that the address is in the valid range for the process. Failure of this test causes an error trap to the operating system.

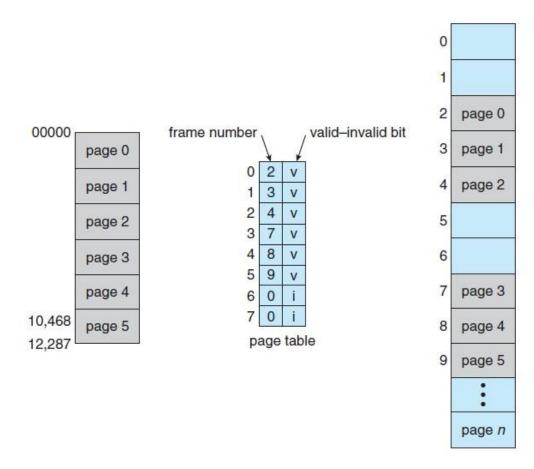


Figure 7-15 Valid (v) or invalid (i) bit in a page table

## **Chapter Eight**

In the previous chapter we discussed various memory-management strategies used in computer systems. All these strategies have the same goal: to keep many processes in memory simultaneously to allow multiprogramming. However, they tend to require that an entire process be in memory before it can execute.

Virtual memory is a technique that allows the execution of processes that are not completely in memory. One major advantage of this scheme is that programs can be larger than physical memory. Further, virtual memory abstracts main memory into an extremely large, uniform array of storage, separating logical memory as viewed by the user from physical memory. This technique frees programmers from the concerns of memory-storage limitations. Virtual memory also allows processes to share files easily and to implement shared memory. In addition, it provides an efficient mechanism for process creation. Virtual memory is not easy to implement, however, and may substantially decrease performance if it is used carelessly. In this chapter, we discuss virtual memory in the form of demand paging and examine its complexity and cost.

## 8.1. Background

The memory-management algorithms outlined in Chapter 7 are necessary because of one basic requirement: The instructions being executed must be in physical memory. The first approach to meeting this requirement is to place the entire logical address space in physical memory. Dynamic loading can help to ease this restriction, but it generally requires special precautions and extra work by the programmer. The requirement that instructions must be in physical memory to be executed seems both necessary and reasonable; but it is also unfortunate, since it limits the size of a program to the size of physical memory. In fact, an examination of real programs shows us that, in many cases, the entire program is not needed. For instance, consider the following:

• Programs often have code to handle unusual error conditions. Since these errors seldom, if ever, occur in practice, this code is almost never executed.

• Arrays, lists, and tables are often allocated more memory than they actually need. An array may be declared 100 by 100 elements, even though it is seldom larger than 10 by 10 elements. An assembler symbol table may have room for 3,000 symbols, although the average program has less than 200 symbols.

• Certain options and features of a program may be used rarely. For instance, the routines on U.S. government computers that balance the budget have not been used in many years.

Even in those cases where the entire program is needed, it may not all be needed at the same time. The ability to execute a program that is only partially in memory would confer many benefits:

• A program would no longer be constrained by the amount of physical memory that is available. Users would be able to write programs for an extremely large *virtual* address space, simplifying the programming task.

• Because each user program could take less physical memory, more programs could be run at the same time, with a corresponding increase in CPU utilization and throughput but with no increase in response time or turnaround time.

• Less I/O would be needed to load or swap user programs into memory, so each user program would run faster.

Thus, running a program that is not entirely in memory would benefit both the system and the user. **Virtual memory** involves the separation of logical memory as perceived by users from physical memory. This separation allows an extremely large virtual memory to be provided for programmers when only a smaller physical memory is available (Figure 8.1). Virtual memory makes the task of programming much easier, because the programmer no longer needs to worry about the amount of physical memory available; she can concentrate instead on the problem to be programmed. The **virtual address space** of a process refers to the logical (or virtual) view of how a process is stored in memory. Typically, this view is that a process begins at a certain logical address say, address 0 and exists in contiguous memory may be organized in page frames and that the physical page frames assigned to a process may not be contiguous. It is up to the memory management unit (MMU) to map logical pages to physical page frames in memory.

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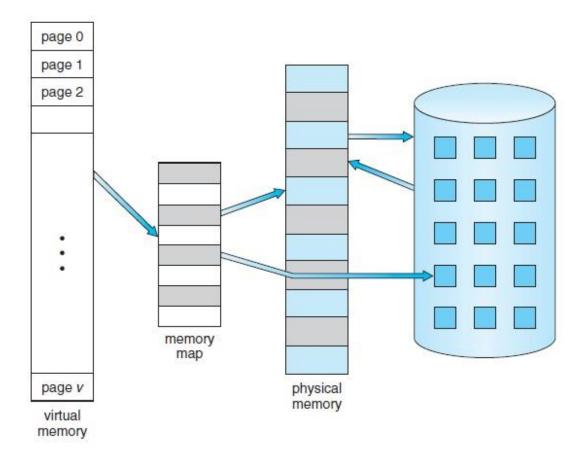


Figure 8-1 Diagram showing virtual memory that is larger than physical memory

## 8.2. Demand Paging

Consider how an executable program might be loaded from disk into memory. One option is to load the entire program in physical memory at program execution time. However, a problem with this approach is that we may not initially *need* the entire program in memory. Suppose a program starts with a list of available options from which the user is to select. Loading the entire program into memory results in loading the executable code for *all* options, regardless of whether or not an option is ultimately selected by the user. An alternative strategy is to load pages only as they are needed. This technique is known as **demand paging** and is commonly used in virtual memory systems.

With demand-paged virtual memory, pages are loaded only when they are demanded during program execution. Pages that are never accessed are thus never loaded into physical memory. A demand-paging system is similar to a paging system