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Linear Algebra with Applications I

References

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by Bernard Kolman.
- 2) Elementary Linear Algebra , by Howard
Anton .
- 3) Linear Algebra , by Fraleigh
- 4) Theory and Problems of Linear Algebra ,
by Seymour Lipschutz .
- 5) 3000 Solved Problems in Linear Algebra ,
by Seymour Lipschutz .
- 6) Introduction to Linear Algebra , by Franz
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S1: Fields

Definition: A binary operation $*$ on a set X is a function $* : X \times X \rightarrow X$.

Definition: A set F with two binary operations $+$ and \cdot defined on F is said to be a field if the following properties are satisfied:

- 1) $a+b \in F \quad \forall a, b \in F$,
- 2) $a+b = b+a \quad \forall a, b \in F$,
- 3) $a+(b+c) = (a+b)+c \quad \forall a, b, c \in F$,
- 4) There exists an element $z \in F$ such that $a+z = z+a \quad \forall a \in F$,
- 5) $\forall a \in F$ there is an element denoted by $-a \in F$ such that $a+(-a) = (-a)+a = z$,
- 6) $a \cdot b \in F \quad \forall a, b \in F$,
- 7) $a \cdot b = b \cdot a \quad \forall a, b \in F$,
- 8) $a \cdot (b \cdot c) = (a \cdot b) \cdot c \quad \forall a, b, c \in F$,
- 9) There exists an element $u \in F$ such that $u \neq z$ and $a \cdot u = u \cdot a = a \quad \forall a \in F$,
- 10) $\forall a \in F - \{z\}$ there exists an element denoted by $a^{-1} \in F$ such that $a \cdot a^{-1} = a^{-1} \cdot a = u$,
- 11) $a \cdot (b+c) = (a \cdot b) + (a \cdot c) \quad \forall a, b, c \in F$.

3. Examples:

- 1) The set \mathbb{R} of all real numbers with the usual addition $+$ and the usual multiplication \cdot of real numbers is a field.
- 2) The set $\mathbb{Q} = \left\{ \frac{p}{q} \mid p \text{ and } q \text{ are integers and } q \neq 0 \right\}$ of all rational numbers with the usual addition $+$ and the usual multiplication \cdot of rational numbers is a field.
- 3) The set $\mathbb{C} = \{a+bi \mid a \text{ and } b \text{ are real numbers}\}$ of all complex numbers with the usual addition $+$ and the usual multiplication \cdot of the complex numbers is a field (notice that $i \cdot i = -1$ and $(a+bi)^{-1} = (a-bi)/(a^2+b^2)$).
- 4) The set \mathbb{R} of all real numbers with the two binary operations $*$ and \circ defined by $a * b = a + b + 1$ and $a \circ b = a \cdot b + a + b$ $\forall a, b \in \mathbb{R}$ is a field.
- 5) The set $\mathbb{Z}_p = \{0, 1, 2, \dots, p-1\}$ with the two binary operations $+_p$ (the addition of integers modulo p) and \cdot_p (the multiplication of integers modulo p) is a field where p is any prime number.
- 6) The set $F_3 = \{4, 8, 12\}$ and $+_{12}'$ and \cdot_{12}' be the two binary operations defined on F_3 as

4. follows:

t_{12}	4	8	12
4	8	12	4
8	12	4	8
12	4	8	12

t_{12}	4	8	12
4	4	8	12
8	8	4	12
12	12	12	12

is a field.

S2: Vectors in the Plane

Definition: A vector in the plane is a 2×1 matrix $X = \begin{pmatrix} x \\ y \end{pmatrix}$ where x and y are real numbers. x is called the first component of X and y is called the second component.

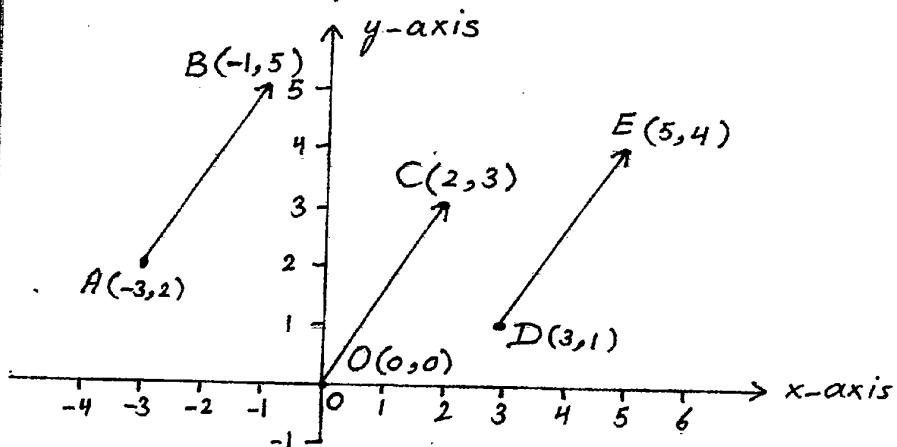
Remarks:

- 1) We can also write the vector X as $X = (x, y)$.
- 2) The set of all vectors in the plane (the Euclidean plane) is denoted by \mathbb{R}^2 .
- 3) The vector $X = \begin{pmatrix} x \\ y \end{pmatrix}$ (or $X = (x, y)$) is represented by the line segment with initial point $O(0, 0)$ and the terminal point $P(x, y)$. The initial point $O(0, 0)$ is called the tail of the vector X and the terminal point $P(x, y)$ is called the head.

5. of the vector X , and X is denoted by \vec{OP} .
 The vector $X = \begin{pmatrix} x \\ y \end{pmatrix}$ is also represented
 by any line segment with initial point
 $A = (a_1, a_2)$ and terminal point $B(a_1 + x, a_2 + y)$
 and A is the tail of the vector X and
 B is the head of the vector X , and X
 is then will be denoted by \vec{AB} .

4) Any vector $X = \begin{pmatrix} x \\ y \end{pmatrix}$ (or $X = (x, y)$) has
 length or magnitude denoted by $\|X\|$
 which is equal $\sqrt{x^2 + y^2}$ (i.e. $\|X\| = \sqrt{x^2 + y^2}$).

Example: The vector $X = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ can be represented
 by any of the following three vectors shown in
 the following figure



Example: Find the length of the vector
 $X = (7, -3)$.

Solution: The length of the vector X is

6. $\|X\| = \sqrt{7^2 + (-3)^2} = \sqrt{49+9} = \sqrt{58}$

Example: Find the length of the vector \vec{PQ} where P is the point $(4, 3)$ and Q is the point $(2, -9)$.

Solution: $\vec{PQ} = (2-4, -9-3) = (-2, -12)$.

$$\therefore \|PQ\| = \sqrt{(-2)^2 + (-12)^2} = \sqrt{4 + 144} = \sqrt{148}.$$

Vector Operations in R^2

Definition: Let $X = (x_1, y_1)$ and $Y = (x_2, y_2)$ be any two vectors in the Euclidean plane. The sum of the vectors X and Y is the vector $(x_1 + x_2, y_1 + y_2)$ and is denoted by $X + Y$.

Example: Find $X + Y$ where X and Y are the vectors $X = (7, 8)$ and $Y = (3, -2)$.

Solution: $X + Y = (7 + 3, 8 - 2) = (10, 6)$.

Definition: If $X = (x, y)$ be any vector in R^2 and c is any scalar ($c \in R$), then the scalar multiple cX of X by c is the vector (cx, cy) (i.e. $cX = (cx, cy)$).

Example: Find $7X$ where $X = (2, 3)$.

7. Solution: $\mathcal{I}X = \mathcal{I}(2, 3) = (14, 21)$.

Remarks:

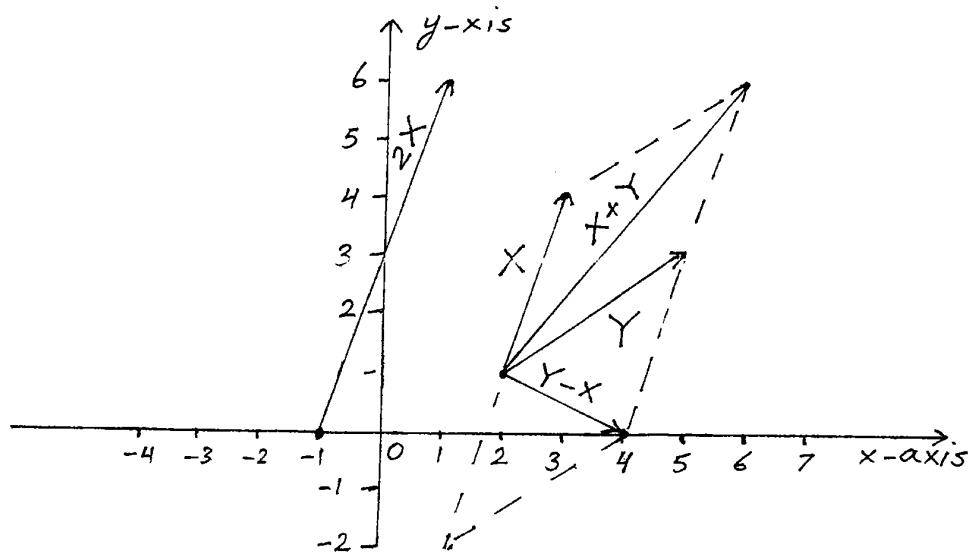
- 1) The vector $O(0, 0)$ is called the zero vector which satisfies that $X + O = X \quad \forall X \in R^2$.
- 2) $\forall X = (x, y) \in R^2$, we have $(-1)X = -1(x, y) = (-x, -y)$. We write $(-1)X$ as $-X$.
- 3) $\forall X, Y \in R^2$ we write $X - Y$ instead of $X + (-Y)$.
- 4) $\forall X \in R^2$, we have $X - X = 0$.

Example: Let $X = (1, 3)$ and $Y = (3, 2)$ and $c = 2$. Find cX , $X + Y$, $Y - X$ and show the answer in a figure.

Solution: $cX = 2X = 2(1, 3) = (2, 6)$.

$$X + Y = (1, 3) + (3, 2) = (4, 5).$$

$$Y - X = (3, 2) - (1, 3) = (2, -1).$$



8. Definition: Two vectors $X = (x_1, y_1)$ and $Y = (x_2, y_2)$ are said to be equal iff $x_1 = x_2$ and $y_1 = y_2$.

Definition: The inner product (or the dot product) of the vectors $X = (x_1, y_1)$ and $Y = (x_2, y_2)$ is $x_1x_2 + y_1y_2$ and is denoted by $X \cdot Y$.

Remarks:

- 1) $X \cdot Y = \|X\| \|Y\| \cos \theta$ where θ is the angle between the nonzero vectors X and Y and $0 \leq \theta \leq 2\pi$.
- 2) $X \cdot Y = Y \cdot X \quad \forall X, Y \in \mathbb{R}^2$.
- 3) $X \cdot X = \|X\|^2 \geq 0$.
- 4) $X \cdot X = 0$ iff $X = 0$.
- 5) $(X+Y) \cdot Z = X \cdot Z + Y \cdot Z$.
- 6) $(cX) \cdot Y = X \cdot (cY) = c(X \cdot Y)$.

Example: Let $X = (7, 4)$ and $Y = (3, 9)$.

Find $\|X\|$, $\|Y\|$, $X \cdot Y$, and the angle between X and Y .

Solution: $\|X\| = \sqrt{7^2 + 4^2} = \sqrt{49+16} = \sqrt{65}$.

$$\|Y\| = \sqrt{3^2 + 9^2} = \sqrt{9+81} = \sqrt{90}.$$

$$X \cdot Y = (7, 4) \cdot (3, 9) = 21 + 36 = 57$$

$$\cos \theta = \frac{X \cdot Y}{\|X\| \|Y\|} = \frac{57}{\sqrt{65} \sqrt{90}} = \frac{57}{\sqrt{5850}}$$

9. $\therefore \theta = 41.82^\circ$ is the angle between X and Y .

Definition: A unit vector is a vector whose length is 1. If X is any nonzero vector, then the vector $U_X = \frac{X}{\|X\|}$ is the unit vector in the direction of X .

Example: Let $X = (8, -6)$. Find the unit vector in the direction of X .

Solution: $\|X\| = \sqrt{8^2 + (-6)^2} = \sqrt{64+36} = \sqrt{100} = 10$.
Thus $U_X = \frac{1}{10} (8, -6) = (0.8, -0.6)$.

Remarks:

- 1) The unit vector along the positive x -axis is $(1, 0)$ and is denoted by i (i.e. $i = (1, 0)$).
- 2) The unit vector along the positive y -axis is $(0, 1)$ and is denoted by j (i.e. $j = (0, 1)$).
- 3) The two nonzero vectors X and Y are perpendicular (or orthogonal) iff $X \cdot Y = 0$.
- 4) i and j are orthogonal vectors since $i \cdot j = (1, 0) \cdot (0, 1) = 0$
- 5) We can write any vector $X = (x, y)$ as $X = xi + yj$ since $X = (x, y) = (x, 0) + (0, y)$

10. $= x(1, 0) + y(0, 1) = xi + yj$.
 6) i and j are called the standard unit vectors in \mathbb{R}^2 .
Example: Write the vector $X = (7, 12)$ in terms of i and j .
Solution: $X = (7, 12) = 7i + 12j$.

Remarks:

- 1) If the set F with the two binary operations $+$ and \cdot is a field, then this field will be denoted by $(F, +, \cdot)$
- 2) If $(F, +, \cdot)$ is a field, then the set of all vectors $X = (x, y)$ where $x, y \in F$ is denoted by F^2 .

Example: For the field $(\mathbb{Z}_7, +_7, \cdot_7)$, let $X = (3, 2)$ and $Y = (5, 6)$ be two vectors in \mathbb{Z}_7^2 . Find $3X + 4Y$.

Solution:

$$\begin{aligned}
 3X + 4Y &= 3(3, 2) + 4(5, 6) \\
 &= (3, 3, 3, 2) + (4, 5, 4, 6) \\
 &= (2, 6) + (6, 3) \\
 &= (2 +, 6, 6 +, 3) \\
 &= (1, 2)
 \end{aligned}$$

Caution: The definition of the inner product (or the dot product) given in page 8 is not applicable for F^2 if F is neither \mathbb{R} nor \mathbb{Q} .

11. § 3: Vector Spaces

Definition: Let $(F, +, \cdot)$ be a field.

A vector space V over F is a set V together with a binary operation \oplus and an operation of scalar multiplication of the elements of V by the elements of F , such that the following conditions are satisfied:

- 1) $x \oplus y \in V \quad \forall x, y \in V$.
- 2) $x \oplus y = y \oplus x \quad \forall x, y \in V$.
- 3) $x \oplus (y \oplus w) = (x \oplus y) \oplus w \quad \forall x, y, w \in V$.
- 4) There is an element $0 \in V$ such that $v \oplus 0 = 0 \oplus v = v \quad \forall v \in V$.
- 5) $\forall v \in V$ there is an element $-v \in V$ such that $v \oplus -v = -v \oplus v = 0$.
- 6) $cv \in V \quad \forall c \in F$ and $\forall v \in V$.
- 7) $c(bv) = (c \cdot b)v \quad \forall c, b \in F$.
- 8) $(c+b)v = cv \oplus bv \quad \forall c, b \in F$ and $\forall v \in V$.
- 9) $c(v \oplus w) = cv \oplus cw$
- 10) $uv = v \quad \forall v \in V$ and u is the multiplication identity of F .

Definitions:

If V is a vector space over a field $(F, +, \cdot)$ then any element in V is called a vector, the binary operation \oplus defined on V is

12. called vector addition, the elements of F are called scalars, the vector 0 is called the zero vector, the vector $-v$ is called the negative vector.

Remark: Every field is a vector space over itself.

Example 1: The set \mathbb{R} (of all real numbers) together with the usual addition of real numbers and the usual multiplication of real numbers is a vector space over the usual field of real numbers $(\mathbb{R}, +, \cdot)$.

Example 2: The set \mathbb{C} (of all complex numbers) together with the usual addition of complex numbers and the usual multiplication of complex numbers is a vector space over the usual field of complex numbers $(\mathbb{C}, +, \cdot)$.

Example 3: The set \mathbb{Q} (of all rational numbers) together with the usual addition of rational numbers and the usual multiplication of rational numbers is a vector space over the usual field of rational numbers $(\mathbb{Q}, +, \cdot)$.

Example 4: The set $\mathbb{Z}_7 = \{0, 1, 2, 3, 4, 5, 6\}$

13. together with $+$, (the addition of integers modulo 7) and \cdot , (the multiplication of integers modulo 7) is a vector space over the field $(\mathbb{Z}_7, +_7, \cdot_7)$.

Remark: Let $(F, +, \cdot)$ be a field. The set $F^n = \{(x_1, x_2, \dots, x_n) \mid x_1, x_2, \dots, x_n \in F\}$ together with the usual addition $+ : F^n \times F^n \rightarrow F^n$ defined by $(x_1, x_2, \dots, x_n) + (y_1, y_2, \dots, y_n) = (x_1 + y_1, x_2 + y_2, \dots, x_n + y_n)$ and the usual scalar multiplication $\cdot : F \times F^n \rightarrow F^n$ defined by $k \cdot (x_1, x_2, \dots, x_n) = (k \cdot x_1, k \cdot x_2, \dots, k \cdot x_n)$ $\forall k \in F$ and $\forall (x_1, x_2, \dots, x_n) \in F^n$ is a vector space over the field $(F, +, \cdot)$.

Example 5: Show that \mathbb{Z}_{13}^3 together with the usual addition of vectors $+$ and the usual scalar multiplication \cdot is a vector space over the field $(\mathbb{Z}_{13}, +_{13}, \cdot_{13})$.

Solution:

$\forall v = (v_1, v_2, v_3), w = (w_1, w_2, w_3), y = (y_1, y_2, y_3) \in \mathbb{Z}_{13}^3$ and $\forall r, s \in \mathbb{Z}_{13}$, we have.

$$1) v+w = (v_1, v_2, v_3) + (w_1, w_2, w_3) = (v_1 +_{13} w_1, v_2 +_{13} w_2, v_3 +_{13} w_3) \in \mathbb{Z}_{13}^3 \text{ since } v_1 +_{13} w_1, v_2 +_{13} w_2, v_3 +_{13} w_3 \in \mathbb{Z}_{13}$$

$$2) v+w = (v_1, v_2, v_3) + (w_1, w_2, w_3)$$

14. $= (v_1 +_{13} w_1, v_2 +_{13} w_2, v_3 +_{13} w_3)$
 $= (w_1 +_{13} v_1, w_2 +_{13} v_2, w_3 +_{13} v_3)$
 $= (w_1, w_2, w_3) + (v_1, v_2, v_3) = w + v$,
 3) $(v + w) + y$
 $= ((v_1, v_2, v_3) + (w_1, w_2, w_3)) + (y_1, y_2, y_3)$
 $= (v_1 +_{13} w_1, v_2 +_{13} w_2, v_3 +_{13} w_3) + (y_1, y_2, y_3)$
 $= ((v_1 +_{13} w_1) +_{13} y_1, (v_2 +_{13} w_2) +_{13} y_2, (v_3 +_{13} w_3) +_{13} y_3)$
 $= (v_1 +_{13} (w_1 +_{13} y_1), v_2 +_{13} (w_2 +_{13} y_2), v_3 +_{13} (w_3 +_{13} y_3))$
 $= (v_1, v_2, v_3) + (w_1 +_{13} y_1, w_2 +_{13} y_2, w_3 +_{13} y_3)$
 $= (v_1, v_2, v_3) + ((w_1, w_2, w_3) + (y_1, y_2, y_3))$
 $= v + (w + y)$,
 4) $0 = (0, 0, 0)$ since
 $v + 0 = (v_1, v_2, v_3) + (0, 0, 0)$
 $= (v_1 +_{13} 0, v_2 +_{13} 0, v_3 +_{13} 0)$
 $= (v_1, v_2, v_3) = v$,
 5) $-v = (-v_1, -v_2, -v_3)$ (where $-v_i = 13 - v_i$
 when $v_i \neq 0$ while $-0 = 0$) since
 $v + (-v) = (v_1, v_2, v_3) + (-v_1, -v_2, -v_3)$
 $= (v_1 +_{13} -v_1, v_2 +_{13} -v_2, v_3 +_{13} -v_3)$
 $= (0, 0, 0)$,
 6) $r \cdot v = r \cdot (v_1, v_2, v_3)$
 $= (r \cdot_{13} v_1, r \cdot_{13} v_2, r \cdot_{13} v_3) \in \mathbb{Z}_{13}^3$
 since $r \cdot_{13} v_1, r \cdot_{13} v_2, r \cdot_{13} v_3 \in \mathbb{Z}_{13}$,
 7) $r \cdot (s \cdot v) = r \cdot (s \cdot (v_1, v_2, v_3))$
 $= r \cdot (s \cdot_{13} v_1, s \cdot_{13} v_2, s \cdot_{13} v_3)$
 $= (r \cdot_{13} (s \cdot_{13} v_1), r \cdot_{13} (s \cdot_{13} v_2), r \cdot_{13} (s \cdot_{13} v_3))$

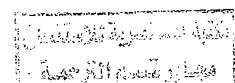
$$\begin{aligned}
 15. &= ((r_{i_3} s)_{i_3} v_1, (r_{i_3} s)_{i_3} v_2, (r_{i_3} s)_{i_3} v_3) \\
 &= (r_{i_3} s) \cdot (v_1, v_2, v_3) \\
 &= (r_{i_3} s) \cdot v
 \end{aligned}$$

$$\begin{aligned}
 8) & (r +_{i_3} s) \cdot v \\
 &= (r +_{i_3} s) \cdot (v_1, v_2, v_3) \\
 &= ((r +_{i_3} s)_{i_3} v_1, (r +_{i_3} s)_{i_3} v_2, (r +_{i_3} s)_{i_3} v_3) \\
 &= ((r_{i_3} v_1) +_{i_3} (s_{i_3} v_1), (r_{i_3} v_2) +_{i_3} (s_{i_3} v_2), (r_{i_3} v_3) +_{i_3} (s_{i_3} v_3)) \\
 &= (r_{i_3} v_1, r_{i_3} v_2, r_{i_3} v_3) + (s_{i_3} v_1, s_{i_3} v_2, s_{i_3} v_3) \\
 &= r \cdot (v_1, v_2, v_3) + s \cdot (v_1, v_2, v_3) \\
 &= r \cdot v + s \cdot v
 \end{aligned}$$

$$\begin{aligned}
 9) & r \cdot (v + w) \\
 &= r \cdot ((v_1, v_2, v_3) + (w_1, w_2, w_3)) \\
 &= r \cdot (v_1 +_{i_3} w_1, v_2 +_{i_3} w_2, v_3 +_{i_3} w_3) \\
 &= (r_{i_3} (v_1 +_{i_3} w_1), r_{i_3} (v_2 +_{i_3} w_2), r_{i_3} (v_3 +_{i_3} w_3)) \\
 &= ((r_{i_3} v_1) +_{i_3} (r_{i_3} w_1), (r_{i_3} v_2) +_{i_3} (r_{i_3} w_2), (r_{i_3} v_3) +_{i_3} (r_{i_3} w_3)) \\
 &= (r_{i_3} v_1, r_{i_3} v_2, r_{i_3} v_3) + (r_{i_3} w_1, r_{i_3} w_2, r_{i_3} w_3) \\
 &= r \cdot v_1 + r \cdot v_2
 \end{aligned}$$

$$\begin{aligned}
 10) & 1 \cdot v \\
 &= 1 \cdot (v_1, v_2, v_3) \\
 &= (1_{i_3} v_1, 1_{i_3} v_2, 1_{i_3} v_3) \\
 &= (v_1, v_2, v_3) = v
 \end{aligned}$$

Thus $\mathbb{Z}_{i_3}^3$ together with the usual addition of vectors $+$ and the usual scalar multiplication is a vector space over the field $(\mathbb{Z}_{i_3}, +_{i_3}, \cdot_{i_3})$.



16. Example 6: Show that \mathbb{Q}^4 together with the usual addition of vectors + and the usual scalar multiplication \cdot is a vector space over the usual field of rational numbers $(\mathbb{Q}, +, \cdot)$.

Solution:

$\forall \mathbf{v} = (v_1, v_2, v_3, v_4), \mathbf{w} = (w_1, w_2, w_3, w_4),$
 $\mathbf{y} = (y_1, y_2, y_3, y_4) \in \mathbb{Q}^4$ and $\forall r, s \in \mathbb{Q}$, we have:

$$1) \mathbf{v} + \mathbf{w} = (v_1, v_2, v_3, v_4) + (w_1, w_2, w_3, w_4) \\ = (v_1 + w_1, v_2 + w_2, v_3 + w_3, v_4 + w_4) \in \mathbb{Q}^4$$

since $v_1 + w_1, v_2 + w_2, v_3 + w_3, v_4 + w_4 \in \mathbb{Q}$,

$$2) \mathbf{v} + \mathbf{w} = (v_1, v_2, v_3, v_4) + (w_1, w_2, w_3, w_4) \\ = (v_1 + w_1, v_2 + w_2, v_3 + w_3, v_4 + w_4) \\ = (w_1 + v_1, w_2 + v_2, w_3 + v_3, w_4 + v_4) \\ = (w_1, w_2, w_3, w_4) + (v_1, v_2, v_3, v_4) = \mathbf{w} + \mathbf{v}$$

$$3) (\mathbf{v} + \mathbf{w}) + \mathbf{y} \\ = ((v_1, v_2, v_3, v_4) + (w_1, w_2, w_3, w_4)) + (y_1, y_2, y_3, y_4) \\ = (v_1 + w_1, v_2 + w_2, v_3 + w_3, v_4 + w_4) + (y_1, y_2, y_3, y_4) \\ = ((v_1 + w_1) + y_1, (v_2 + w_2) + y_2, (v_3 + w_3) + y_3, (v_4 + w_4) + y_4) \\ = (v_1 + (w_1 + y_1), v_2 + (w_2 + y_2), v_3 + (w_3 + y_3), v_4 + (w_4 + y_4)) \\ = (v_1, v_2, v_3, v_4) + (w_1, w_2, w_3, w_4) + (y_1, y_2, y_3, y_4) \\ = \mathbf{v} + (\mathbf{w} + \mathbf{y}),$$

$$4) \mathbf{0} = (0, 0, 0, 0) \text{ since}$$

$$\mathbf{v} + \mathbf{0} = (v_1, v_2, v_3, v_4) + (0, 0, 0, 0)$$

17.

$$5) -U = (-U_1, -U_2, -U_3, -U_4) \text{ since}$$

$$\begin{aligned} U + (-U) &= (U_1, U_2, U_3, U_4) + (-U_1, -U_2, -U_3, -U_4) \\ &= (U_1 - U_1, U_2 - U_2, U_3 - U_3, U_4 - U_4) \\ &= (0, 0, 0, 0) = O \end{aligned}$$

$$6) r \cdot U = r \cdot (U_1, U_2, U_3, U_4)$$

$$\begin{aligned} &= (r \cdot U_1, r \cdot U_2, r \cdot U_3, r \cdot U_4) \in \mathbb{Q}^4 \text{ since} \\ &r \cdot U_1, r \cdot U_2, r \cdot U_3, r \cdot U_4 \in \mathbb{Q} \end{aligned}$$

$$7) r \cdot (s \cdot U) = r \cdot (s \cdot (U_1, U_2, U_3, U_4))$$

$$\begin{aligned} &= r \cdot (s \cdot U_1, s \cdot U_2, s \cdot U_3, s \cdot U_4) \\ &= (r \cdot (s \cdot U_1), r \cdot (s \cdot U_2), r \cdot (s \cdot U_3), r \cdot (s \cdot U_4)) \\ &= ((r \cdot s) \cdot U_1, (r \cdot s) \cdot U_2, (r \cdot s) \cdot U_3, (r \cdot s) \cdot U_4) \\ &= (r \cdot s) \cdot (U_1, U_2, U_3, U_4) \\ &= (r \cdot s) \cdot U \end{aligned}$$

$$8) (r+s) \cdot U$$

$$= (r+s) \cdot (U_1, U_2, U_3, U_4)$$

$$= ((r+s) \cdot U_1, (r+s) \cdot U_2, (r+s) \cdot U_3, (r+s) \cdot U_4)$$

$$= (r \cdot U_1 + s \cdot U_1, r \cdot U_2 + s \cdot U_2, r \cdot U_3 + s \cdot U_3, r \cdot U_4 + s \cdot U_4)$$

$$= (r \cdot U_1, r \cdot U_2, r \cdot U_3, r \cdot U_4) + (s \cdot U_1, s \cdot U_2, s \cdot U_3, s \cdot U_4)$$

$$= r \cdot U + s \cdot U$$

$$9) r \cdot (U + W)$$

$$= r \cdot ((U_1, U_2, U_3, U_4) + (W_1, W_2, W_3, W_4))$$

$$= r \cdot (U_1 + W_1, U_2 + W_2, U_3 + W_3, U_4 + W_4)$$

$$= (r \cdot (U_1 + W_1), r \cdot (U_2 + W_2), r \cdot (U_3 + W_3), r \cdot (U_4 + W_4))$$

$$= (r \cdot U_1 + r \cdot W_1, r \cdot U_2 + r \cdot W_2, r \cdot U_3 + r \cdot W_3, r \cdot U_4 + r \cdot W_4)$$

$$= (r \cdot U_1, r \cdot U_2, r \cdot U_3, r \cdot U_4) + (r \cdot W_1, r \cdot W_2, r \cdot W_3, r \cdot W_4)$$

$$18. = r \cdot (v_1, v_2, v_3, v_4) + r \cdot (w_1, w_2, w_3, w_4)$$

$$= r \cdot v + r \cdot w$$

$$10) 1 \cdot v$$

$$= 1 \cdot (v_1, v_2, v_3, v_4)$$

$$= (1 \cdot v_1, 1 \cdot v_2, 1 \cdot v_3, 1 \cdot v_4)$$

$$= (v_1, v_2, v_3, v_4)$$

$$= v$$

Thus \mathbb{Q}^4 together with the usual addition of vectors $+$ and the usual scalar multiplication \cdot is a vector space over the usual field of rational numbers $(\mathbb{Q}, +, \cdot)$.

Remark: Let $(F, +, \cdot)$ be a field. The set $V = \underbrace{M_{m \times n}(F)}$ of all $m \times n$ matrices over the field $(F, +, \cdot)$ (i.e. the entries of the matrices belong to F) together with the usual addition of matrices and the usual scalar multiplication of matrices by scalars is a vector space over the field $(F, +, \cdot)$.

Example 7: Show that $M_{2 \times 2}(R)$ together with the usual addition of matrices and the usual scalar multiplication of matrices by scalars is a vector space over the

19. usual field of real numbers $(\mathbb{R}, +, \cdot)$.

Solution:

$\forall U = \begin{pmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{pmatrix}$, $W = \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix}$, $Y = \begin{pmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{pmatrix} \in M_{2 \times 2}(\mathbb{R})$
and $\forall r, s \in \mathbb{R}$, we have

$$1) U + W = \begin{pmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{pmatrix} + \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} = \begin{pmatrix} u_{11} + w_{11} & u_{12} + w_{12} \\ u_{21} + w_{21} & u_{22} + w_{22} \end{pmatrix}$$

$\in M_{2 \times 2}(\mathbb{R})$ since $u_{11} + w_{11}, u_{12} + w_{12}, u_{21} + w_{21}, u_{22} + w_{22} \in \mathbb{R}$,

$$\begin{aligned} 2) U + W &= \begin{pmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{pmatrix} + \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} \\ &= \begin{pmatrix} u_{11} + w_{11} & u_{12} + w_{12} \\ u_{21} + w_{21} & u_{22} + w_{22} \end{pmatrix} \\ &= \begin{pmatrix} w_{11} + u_{11} & w_{12} + u_{12} \\ w_{21} + u_{21} & w_{22} + u_{22} \end{pmatrix} \\ &= \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} + \begin{pmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{pmatrix} \\ &= W + U \end{aligned}$$

$$3) (U + W) + Y$$

$$\begin{aligned} &= ((u_{11} & u_{12} \\ u_{21} & u_{22}) + (w_{11} & w_{12} \\ w_{21} & w_{22})) + (y_{11} & y_{12} \\ y_{21} & y_{22}) \\ &= (u_{11} + w_{11} & u_{12} + w_{12} \\ u_{21} + w_{21} & u_{22} + w_{22}) + (y_{11} & y_{12} \\ y_{21} & y_{22}) \\ &= \begin{pmatrix} (u_{11} + w_{11}) + y_{11} & (u_{12} + w_{12}) + y_{12} \\ (u_{21} + w_{21}) + y_{21} & (u_{22} + w_{22}) + y_{22} \end{pmatrix} \end{aligned}$$

$$\begin{aligned}
 20. \quad &= \begin{pmatrix} v_{11} + (w_{11} + y_{11}) & v_{12} + (w_{12} + y_{12}) \\ v_{21} + (w_{21} + y_{21}) & v_{22} + (w_{22} + y_{22}) \end{pmatrix} \\
 &= \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} + \begin{pmatrix} w_{11} + y_{11} & w_{12} + y_{12} \\ w_{21} + y_{21} & w_{22} + y_{22} \end{pmatrix} \\
 &= \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} + \left(\begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} + \begin{pmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{pmatrix} \right) \\
 &= U + (W + Y)
 \end{aligned}$$

4) $O = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ since

$$\begin{aligned}
 U + O &= \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \\
 &= \begin{pmatrix} v_{11} + 0 & v_{12} + 0 \\ v_{21} + 0 & v_{22} + 0 \end{pmatrix} \\
 &= \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} = U
 \end{aligned}$$

5) $-U = \begin{pmatrix} -v_{11} & -v_{12} \\ -v_{21} & -v_{22} \end{pmatrix}$ since

$$\begin{aligned}
 U + (-U) &= \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} + \begin{pmatrix} -v_{11} & -v_{12} \\ -v_{21} & -v_{22} \end{pmatrix} \\
 &= \begin{pmatrix} v_{11} - v_{11} & v_{12} - v_{12} \\ v_{21} - v_{21} & v_{22} - v_{22} \end{pmatrix} \\
 &= \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = O
 \end{aligned}$$

6) $r \circ U = r \circ \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} = \begin{pmatrix} r \cdot v_{11} & r \cdot v_{12} \\ r \cdot v_{21} & r \cdot v_{22} \end{pmatrix} \in M_{2 \times 2}(R)$

21. since $r \cdot v_{11}, r \cdot v_{12}, r \cdot v_{21}, r \cdot v_{22} \in R$,

$$\begin{aligned}
 7) \quad r \cdot (s \cdot v) &= r \cdot (s \cdot \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix}) \\
 &= r \cdot \begin{pmatrix} s \cdot v_{11} & s \cdot v_{12} \\ s \cdot v_{21} & s \cdot v_{22} \end{pmatrix} \\
 &= \begin{pmatrix} r \cdot (s \cdot v_{11}) & r \cdot (s \cdot v_{12}) \\ r \cdot (s \cdot v_{21}) & r \cdot (s \cdot v_{22}) \end{pmatrix} \\
 &= \begin{pmatrix} (r \cdot s) \cdot v_{11} & (r \cdot s) \cdot v_{12} \\ (r \cdot s) \cdot v_{21} & (r \cdot s) \cdot v_{22} \end{pmatrix} \\
 &= (r \cdot s) \cdot \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} \\
 &= (r \cdot s) \cdot v,
 \end{aligned}$$

8) $(r+s) \cdot v$

$$\begin{aligned}
 &= (r+s) \cdot \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} \\
 &= \begin{pmatrix} (r+s) \cdot v_{11} & (r+s) \cdot v_{12} \\ (r+s) \cdot v_{21} & (r+s) \cdot v_{22} \end{pmatrix} \\
 &= \begin{pmatrix} r \cdot v_{11} + s \cdot v_{11} & r \cdot v_{12} + s \cdot v_{12} \\ r \cdot v_{21} + s \cdot v_{21} & r \cdot v_{22} + s \cdot v_{22} \end{pmatrix} \\
 &= \begin{pmatrix} r \cdot v_{11} & r \cdot v_{12} \\ r \cdot v_{21} & r \cdot v_{22} \end{pmatrix} + \begin{pmatrix} s \cdot v_{11} & s \cdot v_{12} \\ s \cdot v_{21} & s \cdot v_{22} \end{pmatrix} \\
 &= r \cdot \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} + s \cdot \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} = r \cdot v + s \cdot v,
 \end{aligned}$$

22.

$$9) r \cdot (v + w)$$

$$\begin{aligned} &= r \cdot \left(\begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} + \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} \right) \\ &= r \cdot \begin{pmatrix} v_{11} + w_{11} & v_{12} + w_{12} \\ v_{21} + w_{21} & v_{22} + w_{22} \end{pmatrix} \\ &= \begin{pmatrix} r \cdot (v_{11} + w_{11}) & r \cdot (v_{12} + w_{12}) \\ r \cdot (v_{21} + w_{21}) & r \cdot (v_{22} + w_{22}) \end{pmatrix} \\ &= \begin{pmatrix} r \cdot v_{11} + r \cdot w_{11} & r \cdot v_{12} + r \cdot w_{12} \\ r \cdot v_{21} + r \cdot w_{21} & r \cdot v_{22} + r \cdot w_{22} \end{pmatrix} \\ &= \begin{pmatrix} r \cdot v_{11} & r \cdot v_{12} \\ r \cdot v_{21} & r \cdot v_{22} \end{pmatrix} + \begin{pmatrix} r \cdot w_{11} & r \cdot w_{12} \\ r \cdot w_{21} & r \cdot w_{22} \end{pmatrix} \\ &= r \cdot \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} + r \cdot \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} \\ &= r \cdot v + r \cdot w \end{aligned}$$

$$10) 1 \cdot v = 1 \cdot \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} = \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} = v$$

Thus $M_{2 \times 2}(R)$ together with the usual addition of matrices and the usual scalar multiplication of matrices by scalar is a vector space over the usual field of real numbers $(R, +, \cdot)$.

Remark: Let $(F, +, \cdot)$ be a field. The set $F[x]$ of all polynomials in x over the field

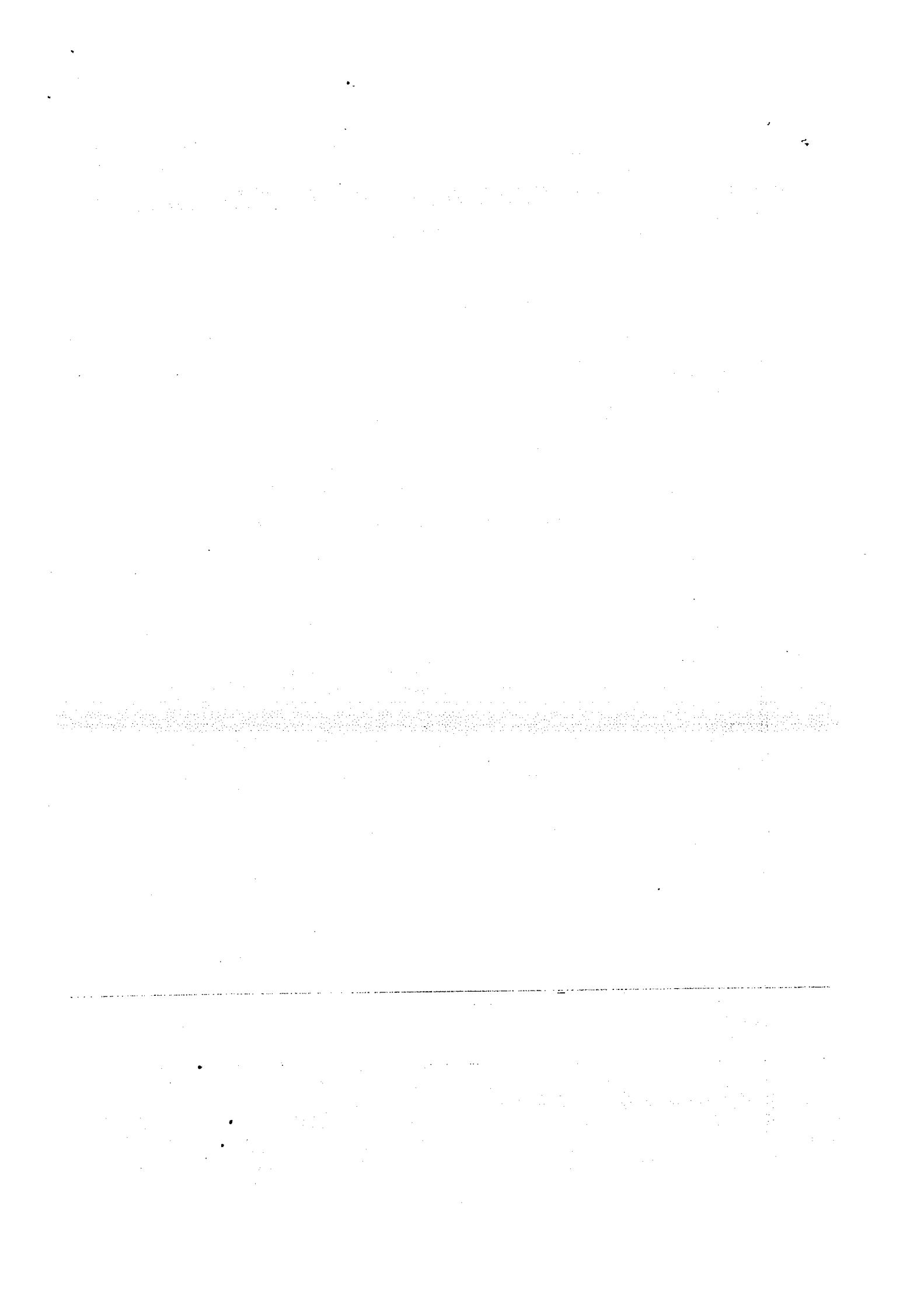
23. $(F, +, \cdot)$ (i.e. $F[x]$ is the set of all functions that can be expressed as $p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$ where $a_0, a_1, \dots, a_n \in F$) is a vector space over the field $(F, +, \cdot)$.

Remarks:

- 1) Every vector space V over the usual field of complex numbers is also a vector space over the usual field of real numbers and also a vector space over the usual field of rational numbers.
- 2) Every vector space V over the usual field of real numbers is also a vector space over the usual field of rational numbers.

Theorem 1: Let the set V together with the binary operation $+$ and the scalar multiplication \cdot (multiplication of vectors by scalars) be a vector space over a field $(F, +, \cdot)$, then:

- i) The identity element (with respect to $+$) is unique.
- ii) Each element v of V has exactly one inverse element (with respect to $+$).
- iii) If $v, w, y \in V$ and $y+v=y+w$ then $v=w$.
- iv) If $v, w, y \in V$ and $v+y=w+y$ then $v=w$.
- v) $\exists \cdot v=0 \quad \forall v \in V$.



24. vi) $k \cdot 0 = 0 \quad \forall k \in F$.
 vii) If $k \cdot v = 0$ then $k = z$ or $v = 0$.
 viii) $(-u) \cdot v = -v \quad \forall v \in V$.

Proof:

i) Assume that V has two identity elements 0 and e , then we have

$$v + 0 = 0 + v = v \quad \text{and} \quad v + e = e + v = v \quad \left. \right\} \quad \forall v \in V.$$

$$\text{Hence } e = 0 + e = 0.$$

Thus the identity element is unique

ii) Let $v \in V$ and assume that v has two inverses $-v$ and w , then we have

$$v + -v = -v + v = 0$$

$$\text{and } v + w = w + v = 0$$

$$\text{Hence } -v = -v + 0$$

$$= -v + (v + w)$$

$$= (-v + v) + w$$

$$= 0 + w$$

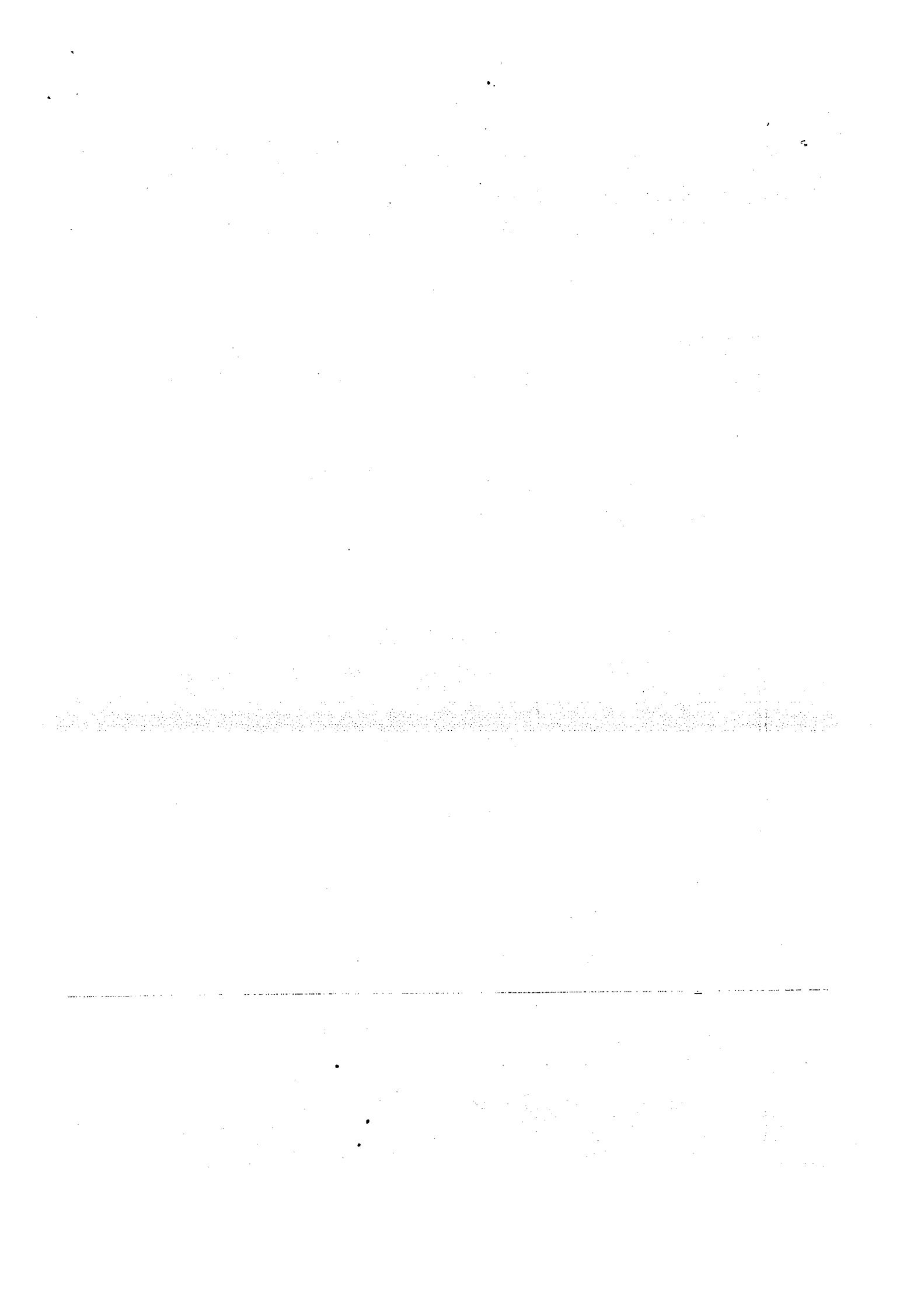
$$= w.$$

Thus v has only one inverse element.

iii) If $y + v = y + w$, then

$$v = 0 + v$$

$$= (-y + y) + v$$



25.

$$\begin{aligned}
 &= -y + (y + v) \\
 &= -y + (y + w) \\
 &= (-y + y) + w \\
 &= 0 + w \\
 &= w
 \end{aligned}$$

iv) If $v + y = w + y$, then

$$\begin{aligned}
 v &= v + 0 \\
 &= v + (y + -y) \\
 &= (v + y) + -y \\
 &= (w + y) + -y \\
 &= w + (y + -y) \\
 &= w + 0 \\
 &= w
 \end{aligned}$$

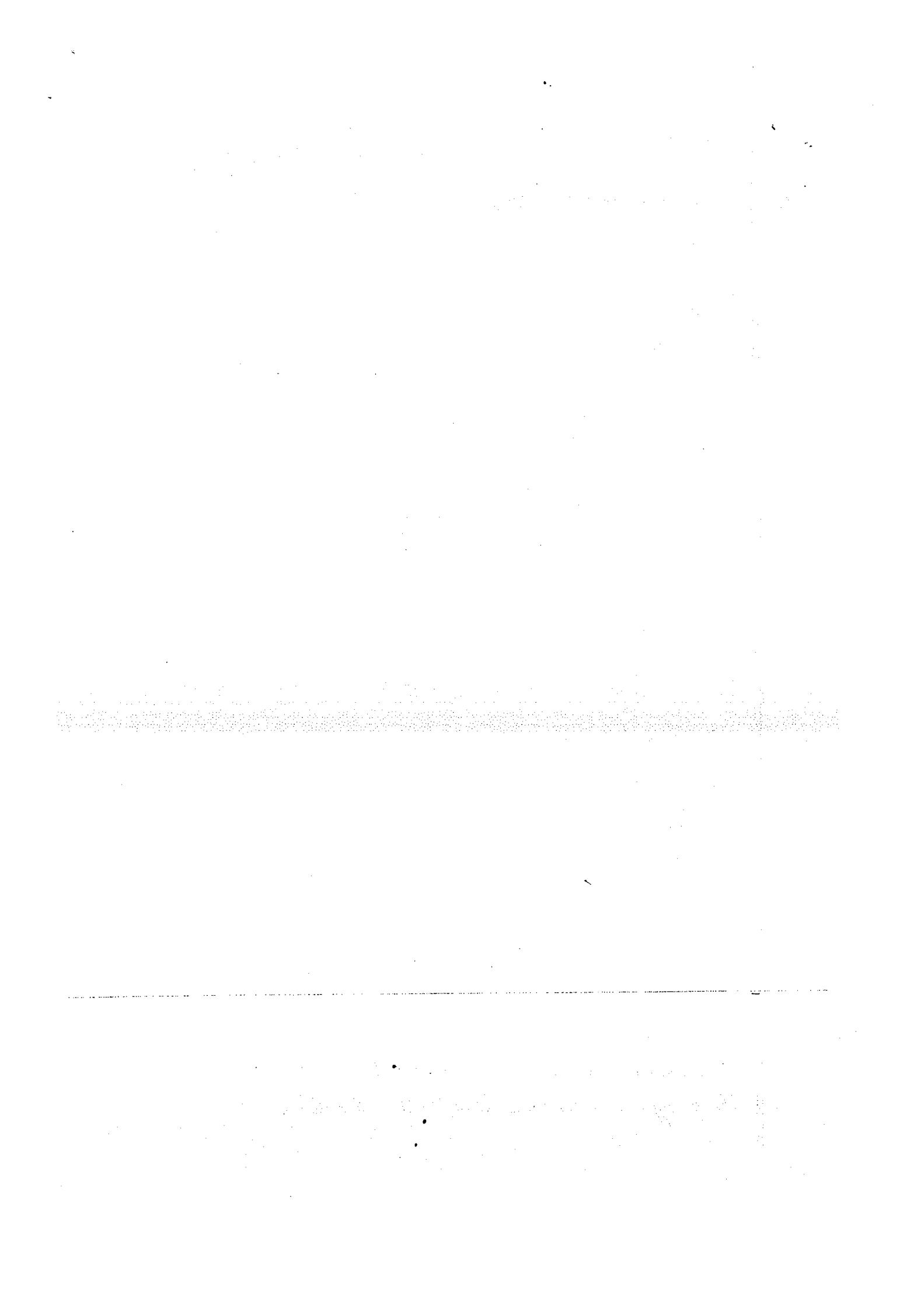
v) $0 + (z \cdot v)$

$$\begin{aligned}
 &= z \cdot v \\
 &= (z + z) \cdot v \\
 &= (z \cdot v) + (z \cdot v) \quad \forall v \in V
 \end{aligned}$$

Then by (iv) above $0 = z \cdot v \quad \forall v \in V$.vi) $0 + (k \cdot 0)$

$$\begin{aligned}
 &= k \cdot 0 \\
 &= k \cdot (0 + 0) \\
 &= (k \cdot 0) + (k \cdot 0) \quad \forall k \in F
 \end{aligned}$$

Then by (iv) above $0 = k \cdot 0 \quad \forall k \in F$



26. vii) By (v) above $k \cdot v = 0$ when $k=0$.

Assume that $k \cdot v = 0$ and $k \neq 0$, then

$$0 = \frac{1}{k} \cdot 0 \quad \text{by (vi) above}$$

$$= \frac{1}{k} \cdot (k \cdot v)$$

$$= \left(\frac{1}{k} \cdot k\right) \cdot v$$

$$= u \cdot v$$

$$= v$$

viii) $(-u) \cdot v$

$$= (-u) \cdot v + 0$$

$$= (-u) \cdot v + (v + -v)$$

$$= ((-u) \cdot v + v) + -v$$

$$= ((-u) \cdot v + u \cdot v) + -v$$

$$= (-u + u) \cdot v + -v$$

$$= 0 \cdot v + -v$$

$$= 0 + -v$$

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S4: Subspaces

Definition: Let V together with a binary operation $+$ defined on V and a scalar

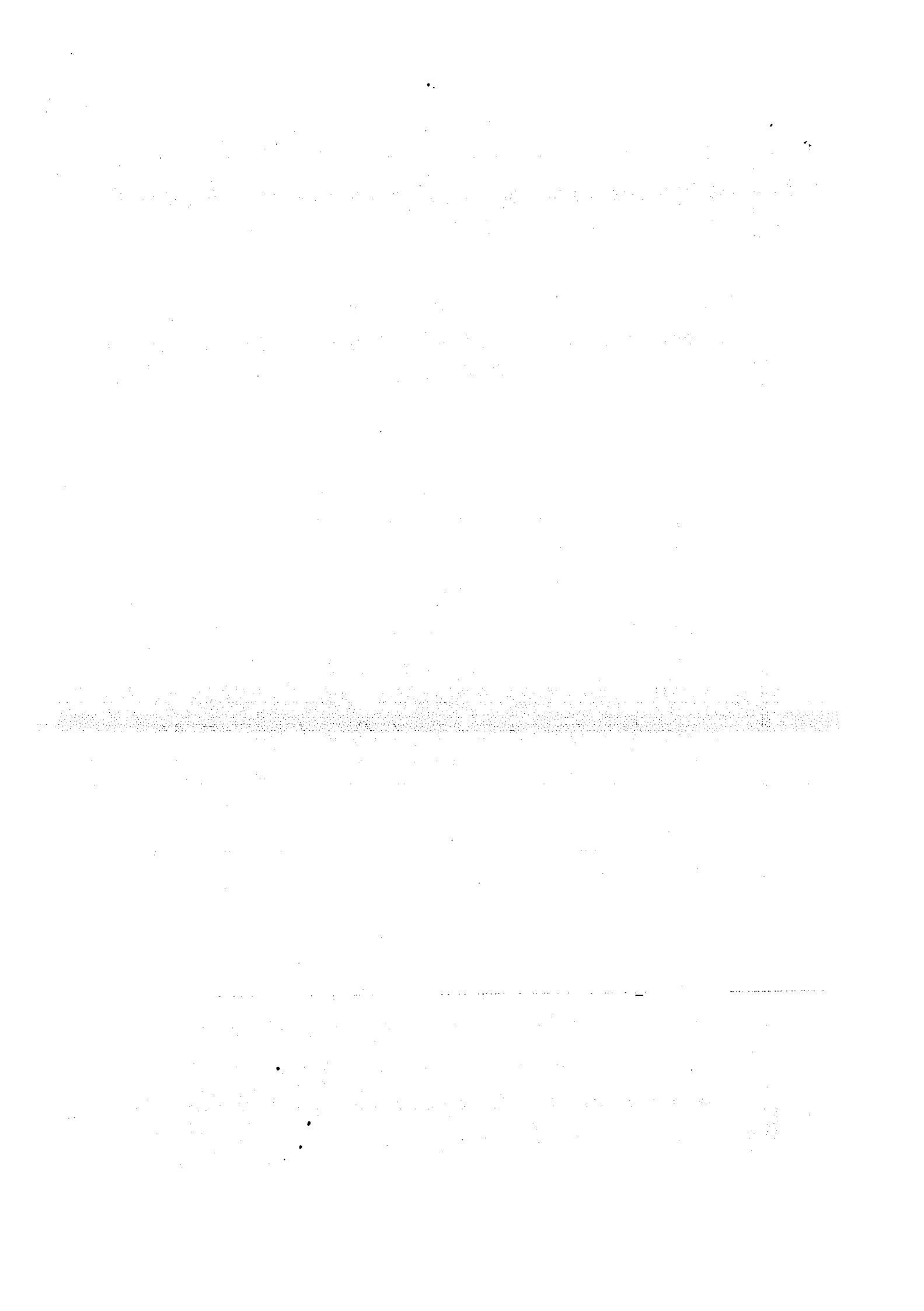


27. multiplication \cdot be a vector space over a field $(F, +, \cdot)$ and let W be a nonempty subset of V . If W is a vector space over the same field $(F, +, \cdot)$ with respect to the same operations $+$ and \cdot of the vector space V , then W is called a subspace of V .

Theorem 2: W is a subspace of a vector space V over a field $(F, +, \cdot)$ iff

- i) W is a nonempty subset of V (i.e. $\phi \neq W \subseteq V$).
- ii) W is closed under the binary operation $+$ defined on V (i.e. $v + w \in W \quad \forall v, w \in W$).
- iii) W is closed under the scalar multiplication \cdot defined on $F \times V$ (i.e. $k \cdot v \in W \quad \forall k \in F$ and $\forall v \in W$)

Proof: If W is a subspace of V then by the definition of subspace $W \subseteq V$ and W is a vector space under the binary operation $+$ defined on V and the scalar multiplication \cdot defined on $F \times V$ (i.e. $\cdot : F \times V \rightarrow V$). Hence by the definition of vector space W is nonempty which is a subset of V (i.e. (i) is satisfied), and



28. $v+w \in W \quad \forall v, w \in W$ by the first property of the definition of vector space (i.e. (ii) is satisfied) and $k \cdot v \in W \quad \forall k \in F$ and $v \in W$ by the sixth property of the definition of vector space (i.e. (iii) is satisfied).

Conversely, if W satisfies (i), (ii), and (iii) then $W \neq \emptyset$ and

- 1) $\forall v, w \in W$ we have $v+w \in W$ by (i).
- 2) $\forall v, w \in W$ we have $v, w \in V$ (since $W \subseteq V$) and hence $v+w=w+v$.
- 3) $\forall v, w, y \in W$ we have $v, w, y \in V$ (since $W \subseteq V$) and hence $v+(w+y)=(v+w)+y$.
- 4) Since $W \neq \emptyset$ then there exists $w \in W$. Hence by (iii) $z \cdot w = 0 \in W$ and $\forall v \in W$ we have $v \in V$ (since $W \subseteq V$) and thus $v+0=v$.
- 5) $\forall v \in W$ we have by (iii) $-v \cdot v = -v$ and $v+(-v)=0$.
- 6) $\forall k \in F$ and $\forall v \in W$ we have $k \cdot v \in W$ by (iii).
- 7) $\forall k \in F$ and $\forall v, w \in W$ we have $v, w \in V$, hence $k \cdot (v+w)=k \cdot v+k \cdot w$.
- 8) $\forall k, l \in F$ and $\forall v \in W$ we have $v \in V$, hence $(k+l) \cdot v = k \cdot v + l \cdot v$.
- 9) $\forall k, l \in F$ and $\forall v \in W$ we have $v \in V$, hence $(k \cdot l) \cdot v = k \cdot (l \cdot v)$.



29. 10) $\forall u \in W$ we have $u \in V$, hence $u \cdot v = v$.

Example 1: List all the subspaces of the vector space R^2 over $(R, +, \cdot)$.

Solution: The subspaces of the vector space R^2 over $(R, +, \cdot)$ are:

1) $\{(0, 0)\}$ is a subspace.

2) $\forall k, l \in R \exists (k, l) \neq (0, 0)$ we have

$W_{k,l} = \{(kt, lt) | t \in R\}$ is a subspace.

(i.e. every straight line passing through the origin $O(0, 0)$ of the plane R^2 is a subspace of R^2 over $(R, +, \cdot)$).

3) R^2 is a subspace.

Example 2: List all the subspaces of the vector space R^3 over $(R, +, \cdot)$.

Solution: The subspaces of the vector space R^3 over $(R, +, \cdot)$ are:

1) $\{(0, 0, 0)\}$ is a subspace.

2) $\forall k, l, m \in R \exists (k, l, m) \neq (0, 0, 0)$ we have $W_{k,l,m} = \{(kt, lt, mt) | t \in R\}$ is a subspace. (i.e. every straight line passing through the origin $O(0, 0, 0)$ of the space R^3 over $(R, +, \cdot)$).

3) $\forall k, l, m \in R \exists (k, l, m) \neq (0, 0, 0)$ we

30. have $V_{k,l,m} = \{(x, y, z) \in R^3 \mid kx + lm + mz = 0\}$
is a subspace. (i.e. every plane passing
through the origin $O(0, 0, 0)$ of the space
 R^3 is a subspace R^3 over $(R, +, \cdot)$).
4) R^3 is a subspace.

Example 3: Show that $W = \{(x, 0, z) \mid x, z \in R\}$
is a subspace of the vector space R^3
over $(R, +, \cdot)$.

Solution: The vector $(0, 0, 0) \in W$ since the
second component is 0. Thus $W \neq \emptyset$.

$\forall v = (v_1, 0, v_3), w = (w_1, 0, w_3) \in W$ we
have

$$\begin{aligned} v+w &= (v_1, 0, v_3) + (w_1, 0, w_3) \\ &= (v_1 + w_1, 0, v_3 + w_3) \in W \text{ since } v_1 + w_1, \\ &\quad v_3 + w_3 \in R \text{ and the second component is 0.} \end{aligned}$$

$\forall k \in R$ and $\forall v = (v_1, 0, v_3) \in W$ we have
 $k \cdot v = k \cdot (v_1, 0, v_3) = (kv_1, 0, kv_3) \in W$ since
 $kv_1, kv_3 \in R$ and the second component is 0.
Thus by theorem 2, W is a subspace of
 R^3 over $(R, +, \cdot)$.

Example 4: Show that $W = \{(x, y, z) \mid x + y + 2z = 0\}$
is a subspace of the vector space R^3
over $(R, +, \cdot)$.

Solution: The vector $(0, 0, 0) \in W$ since

31. $0+0+2 \times 0 = 0$. Thus $W \neq \emptyset$.

$\forall v = (v_1, v_2, v_3), w = (w_1, w_2, w_3) \in W$ we have

$$v+w = (v_1, v_2, v_3) + (w_1, w_2, w_3)$$

$$= (v_1+w_1, v_2+w_2, v_3+w_3) \in W \text{ since}$$

$$(v_1+w_1) + (v_2+w_2) + 2(v_3+w_3)$$

$$= v_1+w_1+v_2+w_2+2v_3+2w_3$$

$$= v_1+v_2+2v_3+w_1+w_2+2w_3$$

$$= 0+0 \quad \text{since } v=(v_1, v_2, v_3), w=(w_1, w_2, w_3)$$

$\in W$ which means that $v_1+v_2+2v_3=0, w_1+w_2+2w_3=0$.

$$= 0$$

$\forall k \in R$ and $\forall v = (v_1, v_2, v_3) \in W$ we have

$$k \cdot v = k \cdot (v_1, v_2, v_3)$$

$$= (kv_1, kv_2, kv_3) \in W \text{ since}$$

$$kv_1+kv_2+2kv_3$$

$$= k(v_1+v_2+2v_3)$$

$$= k \cdot 0 \quad \text{since } (v_1, v_2, v_3) \in W \text{ which}$$

means that $v_1+v_2+2v_3=0$

$$= 0$$

Thus by theorem 2, W is a subspace of R^3 over $(R, +, \cdot)$.

Example 5: Show that $W = \left\{ \begin{pmatrix} t & s \\ 3t & 5t \end{pmatrix} \mid t, s \in R \right\}$ is a subspace of the vector space $M_{2 \times 2}(R)$ over $(R, +, \cdot)$.

Solution: The matrix $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \in W$. Thus $W \neq \emptyset$.

32. $\forall \begin{pmatrix} t_1 & s_1 \\ 3t_1 & 5t_1 \end{pmatrix}, \begin{pmatrix} t_2 & s_2 \\ 3t_2 & 5t_2 \end{pmatrix} \in W$ we have

$$\begin{pmatrix} t_1 & s_1 \\ 3t_1 & 5t_1 \end{pmatrix} + \begin{pmatrix} t_2 & s_2 \\ 3t_2 & 5t_2 \end{pmatrix} = \begin{pmatrix} t_1 + t_2 & s_1 + s_2 \\ 3t_1 + 3t_2 & 5t_1 + 5t_2 \end{pmatrix}$$

$$= \begin{pmatrix} t_1 + t_2 & s_1 + s_2 \\ 3(t_1 + t_2) & 5(t_1 + t_2) \end{pmatrix} \in W \text{ since } t_1 + t_2, s_1 + s_2 \in R.$$

$\forall k \in R$ and $\forall \begin{pmatrix} t & s \\ 3t & 5t \end{pmatrix} \in W$ we have

$$k \cdot \begin{pmatrix} t & s \\ 3t & 5t \end{pmatrix} = \begin{pmatrix} kt & ks \\ k \cdot 3t & k \cdot 5t \end{pmatrix}$$

$$= \begin{pmatrix} kt & ks \\ 3kt & 5kt \end{pmatrix} \in W \text{ since } kt, ks \in R.$$

§ 5 : Bases and dimension

Definition: Let V be a vector space over a field $(F, +, \cdot)$. A vector w is called a linear combination of the vectors v_1, v_2, \dots, v_m if $w = k_1 v_1 + k_2 v_2 + \dots + k_m v_m$ for some $k_1, k_2, \dots, k_m \in F$.

Example 1: In the vector space \mathbb{R}^3 over $(\mathbb{R}, +, \cdot)$ we have $w = (2, 6, 1)$ is a linear combination of $v_1 = (1, 1, 0)$, $v_2 = (2, 0, 3)$, and $v_3 = (1, 3, 4)$ since
 $3v_1 - v_2 + v_3 = 3(1, 1, 1) - (2, 0, 3) + (1, 3, 4)$

$$\begin{aligned}
 33. &= (3, 3, 0) - (2, 0, 3) + (1, 3, 4) \\
 &= (3-2+1, 3-0+3, 0-3+4) \\
 &= (2, 6, 1)
 \end{aligned}$$

Example 2: In the vector space \mathbb{R}^3 over $(\mathbb{R}, +, \cdot)$, show that $w = (5, 7, -1)$ is a linear combination of the vectors

$v_1 = (1, 1, 1)$, $v_2 = (1, 0, 1)$, and $v_3 = (2, 1, 3)$.

Solution: To show that w is a linear

combination of v_1, v_2, v_3 we should find

$k_1, k_2, k_3 \in \mathbb{R}$ such that $k_1 v_1 + k_2 v_2 + k_3 v_3 = w$.

$$k_1 v_1 + k_2 v_2 + k_3 v_3 = w$$

$$\Rightarrow k_1(1, 1, 1) + k_2(1, 0, 1) + k_3(2, 1, 3) = (5, 7, -1)$$

$$\Rightarrow (k_1, k_1, k_1) + (k_2, 0, k_2) + (2k_3, k_3, 3k_3) = (5, 7, -1)$$

$$\Rightarrow (k_1 + k_2 + 2k_3, k_1 + 0 + k_3, k_1 + k_2 + 3k_3) = (5, 7, -1)$$

$$\Rightarrow k_1 + k_2 + 2k_3 = 5$$

$$k_1 + k_3 = 7$$

$$k_1 + k_2 + 3k_3 = -1$$

by using Cramer's rule we have

$$|A| = \begin{vmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 1 & 1 & 3 \end{vmatrix} = 1 \cdot \begin{vmatrix} 0 & 1 \\ 1 & 3 \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & 1 \\ 1 & 3 \end{vmatrix} + 2 \cdot \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix}$$

$$= 1 \cdot (-1) - 1 \cdot (2) + 2 \cdot (1) = -1 - 2 + 2 = -1.$$

$$|A_1| = \begin{vmatrix} 5 & 1 & 2 \\ 7 & 0 & 1 \\ -1 & 1 & 3 \end{vmatrix} = 5 \cdot \begin{vmatrix} 0 & 1 \\ 1 & 3 \end{vmatrix} - 1 \cdot \begin{vmatrix} 7 & 1 \\ -1 & 3 \end{vmatrix} + 2 \cdot \begin{vmatrix} 7 & 0 \\ -1 & 1 \end{vmatrix}$$

$$34. = 5 \cdot (-1) - 1 \cdot (22) + 2 \cdot (7) = -5 - 22 + 14 = -13$$

$$|A_2| = \begin{vmatrix} 1 & 5 & 2 \\ 1 & 7 & 1 \\ 1 & -1 & 3 \end{vmatrix} = 1 \cdot \begin{vmatrix} 7 & 1 \\ -1 & 3 \end{vmatrix} - 5 \cdot \begin{vmatrix} 1 & 1 \\ 1 & 3 \end{vmatrix} + 2 \cdot \begin{vmatrix} 1 & 7 \\ 1 & -1 \end{vmatrix}$$

$$= 1 \cdot (22) - 5 \cdot (2) + 2 \cdot (-8) = 22 - 10 - 16 = -4$$

$$|A_3| = \begin{vmatrix} 1 & 1 & 5 \\ 1 & 0 & 7 \\ 1 & 1 & -1 \end{vmatrix} = 1 \cdot \begin{vmatrix} 0 & 7 \\ -1 & 1 \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & 7 \\ 1 & -1 \end{vmatrix} + 5 \cdot \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix}$$

$$= 1 \cdot (-7) - 1 \cdot (-8) + 5 \cdot (1) = -7 + 8 + 5 = 6$$

$$\text{Thus } k_1 = \frac{|A_1|}{|A|} = \frac{-13}{-1} = 13, \quad k_2 = \frac{|A_2|}{|A|} = \frac{-4}{-1} = 4,$$

$$\text{and } k_3 = \frac{|A_3|}{|A|} = \frac{6}{-1} = -6.$$

$$\text{Hence } w = 13u_1 + 4u_2 - 6u_3.$$

Definition: Let V be a vector space over a field $(F, +, \cdot)$ and let

$S = \{u_1, u_2, \dots, u_m\} \subseteq V$, then the subspace W of V consisting of all linear combinations of the vectors in S is called the subspace (or the vector space) spanned by u_1, u_2, \dots, u_m and we say that the vectors u_1, u_2, \dots, u_m span W , and we denoted it by $W = \text{span}(S)$ or $W = \text{span}\{u_1, u_2, \dots, u_m\}$.

35. Example: Let $W = \{(x, y, 0) | x, y \in \mathbb{R}\}$ is a subspace of \mathbb{R}^3 over $(\mathbb{R}, +, \cdot)$. Show that $W = \text{span}(S)$, where $S = \{(1, 0, 0), (0, 1, 0)\}$.

Solution: Let $v = (x, y, 0)$ be any vector belongs to W then

$$v = (x, y, 0) = x(1, 0, 0) + y(0, 1, 0).$$

Thus every vector belongs to W is a linear combination of the vectors in S .

Therefore $W = \text{span}(S)$.

Definition: If $S = \{v_1, v_2, \dots, v_m\}$ is a nonempty set of vectors, then the vector equation

$$k_1 v_1 + k_2 v_2 + \dots + k_m v_m = 0$$

has at least one solution which is

$$k_1 = k_2 = \dots = k_m = 0.$$

If this is the only solution, then S is called a linearly independent set. If there are other solutions, then S is called a linearly dependent set.

Theorem 3: Let V be a vector space over a field $(F, +, \cdot)$.

i - A subset S of V with more than one element is linearly dependent iff at least one of the vectors is a linear combination

36. of the other vectors in S .
- ii- A subset S of V with more than one element is linearly independent iff no vector in S is a linear combination of the other vectors in S .
 - iii- A finite subset S of V that contains the zero vector 0 is linearly dependent.
 - iv- A subset S of V with exactly two vectors is linearly independent iff neither vector is a scalar multiple of the other.

Example 1: If $v_1 = (3, 1, 5)$ and $v_2 = (9, 3, 15)$ then the set $S = \{v_1, v_2\}$ in the vector space \mathbb{R}^3 over the field $(\mathbb{R}, +, \cdot)$ is linearly dependent since

$$v_2 = 3v_1$$

Example 2: If $v_1 = (2, 3, 4)$, $v_2 = (1, 1, 2)$ and $v_3 = (3, 5, 6)$ then the set $S = \{v_1, v_2, v_3\}$ in the vector space \mathbb{R}^3 over the field $(\mathbb{R}, +, \cdot)$ is linearly dependent since $2v_1 - v_2 - v_3 = (0, 0, 0) = 0$.

Example 3: Let $\mathbb{Q}[x]$ be the set of all polynomials in x with rational coefficients.

37. $\mathbb{Q}[x]$ is a vector space over the field $(\mathbb{Q}, +, \cdot)$

i- Prove or disprove that the set

$S = \{p_1(x), p_2(x), p_3(x)\}$ which consists of the polynomials $p_1(x) = 1 - x$, $p_2(x) = 2 + 3x - 2x^2$ and $p_3(x) = -\frac{1}{2} + 3x - x^2$ is linearly dependent.

ii- Prove or disprove that the set

$T = \{p_1(x), p_2(x)\}$ where $p_1(x)$ and $p_2(x)$ are the same polynomials given in (i) above is linearly dependent.

Solution:

$$i - k_1 p_1(x) + k_2 p_2(x) + k_3 p_3(x) = 0$$

$$\Rightarrow k_1(1-x) + k_2(2+3x-2x^2) + k_3(-\frac{1}{2}+3x-x^2) = 0$$

$$\Rightarrow k_1 - k_1 x + 2k_2 + 3k_2 x - 2k_2 x^2 - \frac{1}{2}k_3 + 3k_3 x - k_3 x^2 = 0$$

$$\Rightarrow (k_1 + 2k_2 - \frac{1}{2}k_3) + (-k_1 + 3k_2 + 3k_3)x + (-2k_2 - k_3)x^2 = 0$$

$$\Rightarrow k_1 + 2k_2 - \frac{1}{2}k_3 = 0 \quad \dots \textcircled{1}$$

$$-k_1 + 3k_2 + 3k_3 = 0 \quad \dots \textcircled{2}$$

$$-2k_2 - k_3 = 0 \quad \dots \textcircled{3}$$

$$\Rightarrow |A| = \begin{vmatrix} 1 & 2 & -\frac{1}{2} \\ -1 & 3 & 3 \\ 0 & -2 & -1 \end{vmatrix} = 1 \cdot \begin{vmatrix} 3 & 3 \\ -2 & -1 \end{vmatrix} - (-1) \cdot \begin{vmatrix} 1 & 3 \\ 0 & -1 \end{vmatrix} - \frac{1}{2} \cdot \begin{vmatrix} 1 & 3 \\ 0 & -2 \end{vmatrix} \\ = 1 \cdot (3) - 2 \cdot (1) - \frac{1}{2} \cdot (2) = 3 - 2 - 1 = 0$$

which means that we should take only two of the equations $\textcircled{1}$, $\textcircled{2}$, and $\textcircled{3}$ to find the values of k_1 , k_2 , and k_3 , we will take

38. ① and ②

$$\Rightarrow k_1 + 2k_2 = \frac{1}{2}k_3$$

$$-k_1 + 3k_2 = -3k_3$$

$$\Rightarrow |B| = \begin{vmatrix} 1 & 2 \\ -1 & 3 \end{vmatrix} = 3 + 2 = 5$$

$$|B_1| = \begin{vmatrix} \frac{1}{2}k_3 & 2 \\ -3k_3 & 3 \end{vmatrix} = 7.5k_3$$

$$|B_2| = \begin{vmatrix} 1 & \frac{1}{2}k_3 \\ -1 & -3k_3 \end{vmatrix} = -2.5k_3$$

$$\therefore k_1 = \frac{|B_1|}{|B|} = \frac{7.5k_3}{5} = 1.5k_3$$

$$k_2 = \frac{|B_2|}{|B|} = \frac{-2.5k_3}{5} = -0.5k_3$$

take $k_3 = 2$ then $k_1 = 3$ and $k_2 = -1$.

Thus $3p_1(x) - p_2(x) + 2p_3(x) = 0$ which means
that $p_1(x), p_2(x), p_3(x)$ are linearly dependent,
i.e. S is linearly dependent.

i) $k_1 p_1(x) + k_2 p_2(x) = 0$

$$\Rightarrow k_1(1-x) + k_2(2+3x-2x^2) = 0$$

$$\Rightarrow k_1 - k_1x + 2k_2 + 3k_2x - 2k_2x^2 = 0$$

$$\Rightarrow (k_1 + 2k_2) + (-k_1 + 3k_2)x - 2k_2x^2 = 0$$

$$\Rightarrow k_1 + 2k_2 = 0 \quad \dots \textcircled{4}$$

$$-k_1 + 3k_2 = 0 \quad \dots \textcircled{5}$$

$$-2k_2 = 0 \quad \dots \textcircled{6}$$

Multiply equation ⑥ by $-\frac{1}{2}$, we get

39.

$$k_2 = 0 \quad \dots \textcircled{7}$$

substitute $\textcircled{7}$ in $\textcircled{4}$, we get

$$k_1 = 0$$

Thus $k_1 = 0$ and $k_2 = 0$ which means that $p(x)$ and $p(x)$ are linearly independent, i.e. T is linearly independent.

Definition: Let V be a vector space over a field $(F, +, \cdot)$ and $S = \{v_1, v_2, \dots, v_n\}$ is a set of vectors in V , then S is called a basis for V if S is linearly independent and S spans V .

Theorem 4: If $S = \{v_1, v_2, \dots, v_n\}$ is a basis for a vector space V over a field $(F, +, \cdot)$, then every vector v in V can be expressed in the form $v = k_1 v_1 + k_2 v_2 + \dots + k_n v_n$ in exactly one way.

Proof: Every vector v in V can be written as a linear combinations of the vectors in S since S spans V .

Now assume that there is a vector w in V and w can be expressed as a linear combination in two ways as follows

$$w = k_1 v_1 + k_2 v_2 + \dots + k_n v_n \quad \dots \textcircled{1} \quad \text{and}$$

$$w = c_1 v_1 + c_2 v_2 + \dots + c_n v_n \quad \dots \textcircled{2}$$

40. subtracting equation (2) from equation (1), we get

$$(k_1 - c_1)v_1 + (k_2 - c_2)v_2 + \dots + (k_n - c_n)v_n = 0$$

the $k_1 - c_1 = 0, k_2 - c_2 = 0, \dots, k_n - c_n = 0$ since S is linearly independent.

Thus $k_1 = c_1, k_2 = c_2, \dots, k_n = c_n$. Hence w can be expressed in exactly one way as a linear combination of the vectors in S .

Example 1: Prove that $S = \{i, j, k\}$ is a basis for the vector space \mathbb{R}^3 over the field $(\mathbb{R}, +, \cdot)$, where $i = (1, 0, 0)$, $j = (0, 1, 0)$, $k = (0, 0, 1)$.

Solution: S is linearly independent since

$$c_1 i + c_2 j + c_3 k = (0, 0, 0)$$

$$\Rightarrow c_1(1, 0, 0) + c_2(0, 1, 0) + c_3(0, 0, 1) = (0, 0, 0)$$

$$\Rightarrow (c_1, 0, 0) + (0, c_2, 0) + (0, 0, c_3) = (0, 0, 0)$$

$$\Rightarrow (c_1, c_2, c_3) = (0, 0, 0)$$

$$\Rightarrow c_1 = 0, c_2 = 0, \text{ and } c_3 = 0.$$

Also S spans \mathbb{R}^3 since $Hv = (v_1, v_2, v_3) \in \mathbb{R}^3$ we have

$$v = (v_1, v_2, v_3)$$

$$= (v_1, 0, 0) + (0, v_2, 0) + (0, 0, v_3)$$

$$= v_1(1, 0, 0) + v_2(0, 1, 0) + v_3(0, 0, 1)$$

$$= v_1 i + v_2 j + v_3 k$$

Thus S is a basis for the vector space \mathbb{R}^3

41. over the field $(R, +, \cdot)$.

Definition: The set $S = \{e_1, e_2, \dots, e_n\}$ where $e_1 = (1, 0, 0, \dots, 0)$, $e_2 = (0, 1, 0, \dots, 0)$, ..., $e_n = (0, 0, \dots, 0, 1)$ (e_1, e_2, \dots, e_n are n -tuple) is a basis of R^n over the field $(R, +, \cdot)$ which is called the standard basis of R^n over the field $(R, +, \cdot)$.

Example 2: Let $u_1 = (1, 1, 0)$, $u_2 = (0, 1, 1)$, $u_3 = (1, 0, 1)$. Prove that $S = \{u_1, u_2, u_3\}$ is a basis for the vector space R^3 over the field $(R, +, \cdot)$.

Solution:

$$\begin{aligned} k_1 u_1 + k_2 u_2 + k_3 u_3 &= (0, 0, 0) \\ \Rightarrow k_1(1, 1, 0) + k_2(0, 1, 1) + k_3(1, 0, 1) &= (0, 0, 0) \\ \Rightarrow (k_1, k_1, 0) + (0, k_2, k_2) + (k_3, 0, k_3) &= (0, 0, 0) \\ \Rightarrow (k_1 + k_3, k_1 + k_2, k_2 + k_3) &= (0, 0, 0) \\ \Rightarrow k_1 + k_3 &= 0 \\ k_1 + k_2 &= 0 \\ k_2 + k_3 &= 0 \\ \Rightarrow |A| &= \begin{vmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{vmatrix} = 1 \cdot \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} - 0 \cdot \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} \\ &= 1 \cdot (1) - 0 \cdot (1) + 1 \cdot (1) \\ &= 1 - 0 + 1 = 2 \end{aligned}$$

42.

$$|A_1| = \begin{vmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{vmatrix} = 0, |A_2| = \begin{vmatrix} 1 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 0,$$

$$|A_3| = \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{vmatrix} = 0,$$

$$k_1 = \frac{|A_1|}{|A|} = \frac{0}{2} = 0, k_2 = \frac{|A_2|}{|A|} = \frac{0}{2} = 0, k_3 = \frac{|A_3|}{|A|} = \frac{0}{2} = 0.$$

$\Rightarrow S$ is linearly independent.

$\forall U = (U_1, U_2, U_3) \in R^3$, we have.

$$c_1 U_1 + c_2 U_2 + c_3 U_3 = U$$

$$\Rightarrow c_1 \cdot (1, 1, 0) + c_2 \cdot (0, 1, 1) + c_3 \cdot (1, 0, 1) = (U_1, U_2, U_3)$$

$$\Rightarrow (c_1, c_1, 0) + (0, c_2, c_2) + (c_3, 0, c_3) = (U_1, U_2, U_3)$$

$$\Rightarrow (c_1 + c_3, c_1 + c_2, c_2 + c_3) = (U_1, U_2, U_3)$$

$$\Rightarrow c_1 + c_3 = U_1$$

$$c_1 + c_2 = U_2$$

$$c_2 + c_3 = U_3$$

$$\Rightarrow |B| = \begin{vmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{vmatrix} = 2,$$

$$|B_1| = \begin{vmatrix} U_1 & 0 & 1 \\ U_2 & 1 & 0 \\ U_3 & 1 & 1 \end{vmatrix} = U_1 \cdot \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} - 0 \cdot \begin{vmatrix} U_2 & 0 \\ U_3 & 1 \end{vmatrix} + 1 \cdot \begin{vmatrix} U_2 & 1 \\ U_3 & 1 \end{vmatrix} \\ = U_1 + U_2 - U_3,$$

$$|B_2| = \begin{vmatrix} 1 & U_1 & 1 \\ 1 & U_2 & 0 \\ 0 & U_3 & 1 \end{vmatrix} = 1 \cdot \begin{vmatrix} U_2 & 0 \\ U_3 & 1 \end{vmatrix} - U_1 \cdot \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & U_2 \\ 0 & U_3 \end{vmatrix} \\ = U_2 - U_1 + U_3 = -U_1 + U_2 + U_3,$$

43.

$$|B_2| = \begin{vmatrix} 1 & 0 & v_1 \\ 1 & 1 & v_2 \\ 0 & 1 & v_3 \end{vmatrix} = 1 \cdot \begin{vmatrix} 1 & v_2 \\ 0 & v_3 \end{vmatrix} - 0 \cdot \begin{vmatrix} 1 & v_2 \\ 0 & v_3 \end{vmatrix} + v_1 \cdot \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix}$$

$$= v_3 - v_2 + v_1 = v_1 - v_2 + v_3$$

$$\therefore c_1 = \frac{|B_1|}{|B|} = \frac{v_1 + v_2 - v_3}{2}, \quad c_2 = \frac{|B_2|}{|B|} = \frac{-v_1 + v_2 + v_3}{2},$$

$$c_3 = \frac{|B_3|}{|B|} = \frac{-v_1 + v_2 + v_3}{2}$$

Thus S spans \mathbb{R}^3 over the field $(\mathbb{R}, +, \cdot)$.
 Therefore S is a basis for \mathbb{R}^3 over the field $(\mathbb{R}, +, \cdot)$.

Definition: A nonzero vector space V over a field $(\mathbb{R}, +, \cdot)$ is called a finite dimensional, if V contains a finite set of vectors $\{v_1, v_2, \dots, v_n\}$ that forms a basis. If no such finite set exists, then V is called infinite dimensional. The zero vector space is regarded as finite dimensional.

Theorem 5: If V is a finite dimensional vector space and $\{v_1, v_2, \dots, v_n\}$ is any basis for V , then

i- every set with more than n vectors is linearly dependent.

ii- No set with less than n vectors spans V .

44. Theorem 6: All bases for a finite dimensional vector space have the same number of vectors.

Definition: The dimension of a finite dimensional vector space V over a field $(F, +, \cdot)$ is denoted by $\dim_F V$ and is defined to be the number of vectors in a basis for V over the field $(F, +, \cdot)$. The zero vector space defined to have a zero dimension.

Examples:

- 1) $\dim_F F^n = n$, hence we have $\dim_R R^n = n$.
- 2) $\dim_C C^n = n$ and $\dim_R C^n = 2n$, and C^n is of infinite dimension over the field $(Q, +, \cdot)$, for each $n \geq 1$.
- 3) R^n is of infinite dimension over the field $(Q, +, \cdot)$, for each $n \geq 1$.
- 4) $\dim_F M_{m \times n}(F) = mn$ where $M_{m \times n}(F)$ is the vector space of all $m \times n$ matrices over $(F, +, \cdot)$, hence we have $\dim_R M_{m \times n}(R) = mn$ and $\dim_Q M_{m \times n}(Q) = mn$.

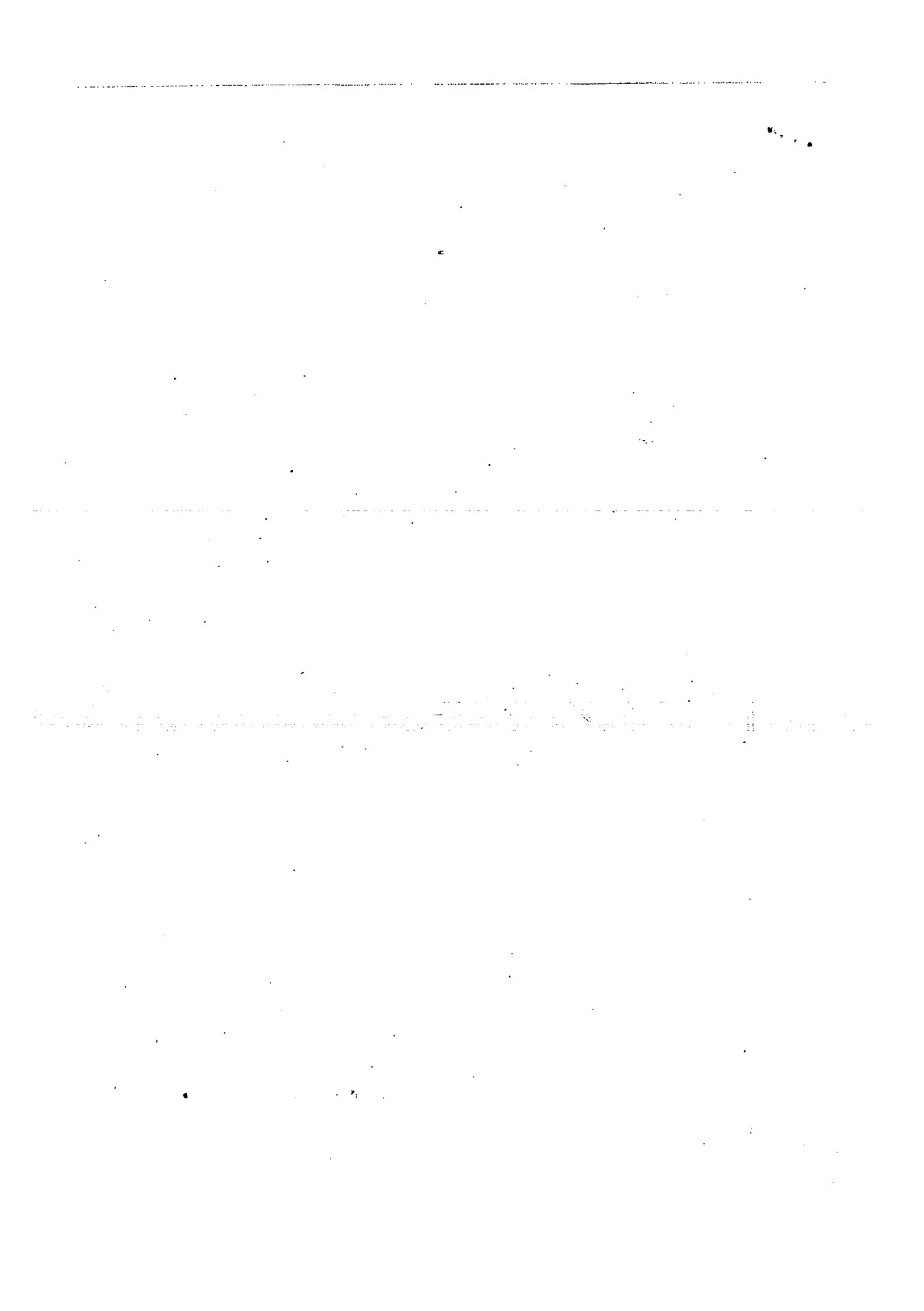
45. Theorem 7: If V is an n -dimensional vector space over a field $(F, +, \cdot)$ and $S = \{v_1, v_2, \dots, v_n\} \subset V$, then S is a basis for V over the field $(F, +, \cdot)$ if either S spans V or S is linearly independent.

S6: Algebra of Subspaces

Definition: Let W_1 and W_2 be subspaces of a vector space V over a field $(F, +, \cdot)$. The set of all vectors v which are in both W_1 and W_2 is called the intersection of the subspaces W_1 and W_2 and is denoted by $W_1 \cap W_2$.

Remark: The intersection $W_1 \cap W_2$ of the subspaces W_1 and W_2 of a vector space V over a field $(F, +, \cdot)$ is never empty since the zero vector 0 belongs to both W_1 and W_2 .

Theorem 8: The intersection of two subspaces W_1 and W_2 of a vector space V over a field $(F, +, \cdot)$ is also a subspace of V over the field $(F, +, \cdot)$.



46. Proof:

Z

line 2

1) The zero vector 0 belongs to W_1 and W_2 which implies that $0 \in W_1 \cap W_2$. Hence $W_1 \cap W_2 \neq \emptyset$.

2) $\forall v_1, v_2 \in W_1 \cap W_2$, we have

$v_1, v_2 \in W_1$ and $v_1, v_2 \in W_2$ which implies that $v_1 + v_2 \in W_1$ and $v_1 + v_2 \in W_2$ since W_1 and W_2 are subspaces of the vector space V over the field $(F, +, \cdot)$.

Thus $v_1 + v_2 \in W_1 \cap W_2$.

3) $\forall r \in F$ and $\forall v \in W_1 \cap W_2$, we have $r \in F$ and $v \in W_1$; $r \in F$ and $v \in W_2$ which implies that $rv \in W_1$ and $rv \in W_2$ since W_1 and W_2 are subspaces of the vector space V over the field $(F, +, \cdot)$.

Thus by theorem 2, $W_1 \cap W_2$ is a subspace of the vector space V over the field $(F, +, \cdot)$.

Example: Let $W_1 = \{(x, y, z) \in \mathbb{R}^3 \mid z=0\}$ and $W_2 = \{(x, y, z) \in \mathbb{R}^3 \mid y=0\}$ be subspaces of the vector space \mathbb{R}^3 over the field $(\mathbb{R}, +, \cdot)$. Find the subspace $W_1 \cap W_2$.

47.

Solution:

$$\begin{aligned} & (x, y, z) \in W_1 \cap W_2 \\ \Rightarrow & (x, y, z) \in W_1 \text{ and } (x, y, z) \in W_2 \\ \Rightarrow & z = 0 \text{ and } y = 0 \\ \Rightarrow & W_1 \cap W_2 = \{(x, 0, 0) \mid x \in \mathbb{R}\} \end{aligned}$$

Definition: Let W_1 and W_2 be subspaces of a vector space V over a field $(F, +, \cdot)$. The subset W of V consisting of all vectors of the form $rv_1 + sv_2$ where $v_1 \in W_1$ and $v_2 \in W_2$ and $r, s \in F$ is called the sum of W_1 and W_2 and denoted by $W_1 + W_2$ (i.e. $W_1 + W_2 = \{rv_1 + sv_2 \mid v_1 \in W_1, v_2 \in W_2, r, s \in F\}$).

Theorem 9: The sum of two subspaces W_1 and W_2 of a vector space V over a field $(F, +, \cdot)$ is also a subspace of V over the field $(F, +, \cdot)$.

Proof: 1) The zero vector 0 belongs to W_1 and W_2 which implies that $1 \cdot 0 + 1 \cdot 0 = 0$ belongs to $W_1 + W_2$ (i.e. $0 \in W_1 + W_2$) i.e. $W_1 + W_2 \neq \emptyset$.

2) If $(r_1v_1 + r_2v_2), (s_1w_1 + s_2w_2) \in W_1 + W_2$, (where $v_1, w_1 \in W_1$, $v_2, w_2 \in W_2$, and $r_1, r_2, s_1, s_2 \in F$), we have

48. $(r_1 v_1 + r_2 v_2) + (s_1 w_1 + s_2 w_2)$
 $= (r_1 v_1 + s_1 w_1) + (r_2 v_2 + s_2 w_2)$
 $= u(r_1 v_1 + s_1 w_1) + u(r_2 v_2 + s_2 w_2) \in W_1 + W_2$,
since $u \in F$ and $(r_1 v_1 + s_1 w_1) \in W_1$ and
 $(r_2 v_2 + s_2 w_2) \in W_2$ because W_1 and W_2 are
subspaces of the vector space V over
the field $(F, +, \cdot)$.

3.) $\forall r \in F$ and $\forall (r_1 v_1 + r_2 v_2) \in W_1 + W_2$,
we have $r(r_1 v_1 + r_2 v_2) = rr_1 v_1 + rr_2 v_2$
 $\in W_1 + W_2$ since $rr_1, rr_2 \in F$, $v_1 \in W_1$,
 $v_2 \in W_2$.

Thus by theorem 2, $W_1 + W_2$ is a subspace
of the vector space V over the field
 $(F, +, \cdot)$.

Example: Let $W_1 = \{(x, 0, 0) | x \in R\}$ and
 $W_2 = \{(0, y, 0) | y \in R\}$ be subspaces of the
vector space R^3 over the field $(R, +, \cdot)$.
Find the subspace $W_1 + W_2$.

Solution:

$$\begin{aligned} W_1 + W_2 &= \{rv_1 + sv_2 | r, s \in R \text{ and } v_1 \in W_1, v_2 \in W_2\} \\ &= \{r(x, 0, 0) + s(0, y, 0) | r, s, x, y \in R\} \\ &= \{(rx, 0, 0) + (0, sy, 0) | r, s, x, y \in R\} \\ &= \{(rx, sy, 0) | r, s, x, y \in R\} \\ &= \{(x_1, x_2, 0) | x_1, x_2 \in R\} \end{aligned}$$

49.

S 7: Orthonormal Bases in R^n

Definition: A set $T = \{v_1, v_2, \dots, v_m\}$ in R^n is called orthogonal if $v_i \cdot v_j = 0$ for $i \neq j$ and $i, j = 1, 2, \dots, m$.

Definition: A set $T = \{v_1, v_2, \dots, v_m\}$ in R^n is called orthonormal if $v_i \cdot v_j = 0$ for $i \neq j$ and $i, j = 1, 2, \dots, m$; and $\|v_j\| = 1$ $\forall j = 1, \dots, m$.

Theorem 10: Let $T = \{v_1, v_2, \dots, v_m\}$ be an orthogonal set of nonzero vectors in R^n . Then T is linearly independent.

Corollary: Let $T = \{v_1, v_2, \dots, v_m\}$ be an orthonormal set of vectors in R^n is linearly independent.

Example: Let $v_1 = (0.6, 0.8, 0, 0)$, $v_2 = (-0.8, 0.6, 0, 0)$, $v_3 = (0, 0, 1, 0)$.

Prove that the set $T = \{v_1, v_2, v_3\}$ is orthonormal.

Solution:

$$\begin{aligned} v_1 \cdot v_2 &= (0.6, 0.8, 0, 0) \cdot (-0.8, 0.6, 0, 0) \\ &= 0.6 \times (-0.8) + 0.8 \times 0.6 + 0 \times 0 + 0 \times 0. \end{aligned}$$

$$= -0.48 + 0.48 + 0 + 0 = 0.$$

50. $U_1 \cdot U_3 = (0.6, 0.8, 0, 0) \cdot (0, 0, 1, 0)$

$$= 0.6 \times 0 + 0.8 \times 0 + 0 \times 1 + 0 \times 0 = 0 + 0 + 0 + 0 = 0$$

$U_2 \cdot U_3 = (-0.8, 0.6, 0, 0) \cdot (0, 0, 1, 0)$

$$= -0.8 \times 0 + 0.6 \times 0 + 0 \times 1 + 0 \times 0 = 0 + 0 + 0 + 0 = 0$$

\therefore The set $T = \{U_1, U_2, U_3\}$ is an orthogonal set.

$$\|U_1\| = \sqrt{(0.6)^2 + (0.8)^2 + (0)^2 + (0)^2}$$

$$= \sqrt{0.36 + 0.64 + 0 + 0} = \sqrt{1} = 1$$

$$\|U_2\| = \sqrt{(-0.8)^2 + (0.6)^2 + (0)^2 + (0)^2}$$

$$= \sqrt{0.64 + 0.36 + 0 + 0} = \sqrt{1} = 1$$

$$\|U_3\| = \sqrt{(0)^2 + (0)^2 + (1)^2 + (0)^2}$$

$$= \sqrt{0 + 0 + 1 + 0} = \sqrt{1} = 1$$

\therefore The set $T = \{U_1, U_2, U_3\}$ is an orthonormal set.

Definition: A basis $B = \{U_1, U_2, \dots, U_n\}$ for \mathbb{R}^n is called an orthogonal basis for \mathbb{R}^n if B is an orthogonal set.

Definition: A basis $B = \{U_1, U_2, \dots, U_n\}$ for \mathbb{R}^n is called an orthonormal basis for \mathbb{R}^n if B is an orthonormal set.

Example: Let $U_1 = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0)$,
 $U_2 = (-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0)$, $U_3 = (0, 0, 1)$. Prove that the basis $B = \{U_1, U_2, U_3\}$ is an orthonormal.

51. basis.

Solution:

$$\begin{aligned} \mathbf{v}_1 \cdot \mathbf{v}_2 &= \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right) \cdot \left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right) \\ &= -\frac{1}{2} + \frac{1}{2} + 0 = 0 \end{aligned}$$

$$\begin{aligned} \mathbf{v}_1 \cdot \mathbf{v}_3 &= \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right) \cdot (0, 0, 1) = \frac{1}{\sqrt{2}}(0) + \frac{1}{\sqrt{2}}(0) + 0(1) \\ &= 0 + 0 + 0 = 0 \end{aligned}$$

$$\begin{aligned} \mathbf{v}_2 \cdot \mathbf{v}_3 &= \left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right) \cdot (0, 0, 1) \\ &= -\frac{1}{\sqrt{2}}(0) + \frac{1}{\sqrt{2}}(0) + 0(1) = 0 + 0 + 0 = 0 \end{aligned}$$

\therefore The basis $B = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthogonal basis.

$$\|\mathbf{v}_1\| = \sqrt{\left(\frac{1}{\sqrt{2}}\right)^2 + \left(\frac{1}{\sqrt{2}}\right)^2 + (0)^2} = \sqrt{\frac{1}{2} + \frac{1}{2} + 0} = \sqrt{1} = 1.$$

$$\|\mathbf{v}_2\| = \sqrt{\left(-\frac{1}{\sqrt{2}}\right)^2 + \left(\frac{1}{\sqrt{2}}\right)^2 + (0)^2} = \sqrt{\frac{1}{2} + \frac{1}{2} + 0} = \sqrt{1} = 1.$$

$$\|\mathbf{v}_3\| = \sqrt{(0)^2 + (0)^2 + (1)^2} = \sqrt{0 + 0 + 1} = \sqrt{1} = 1.$$

\therefore The basis $B = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthonormal basis.

S 8: Linear Transformation and Matrices

Definition: Let V and W be two vector spaces over the same field $(F, +, \cdot)$.

A function $f: V \rightarrow W$ is called a linear

(52. transformation (or linear mapping or vector space homomorphism) if f satisfies the following:

- (1) $f(w+u) = f(w) + f(u)$ $\forall w, u \in V$
- (2) $f(rv) = rf(u)$ $\forall r \in F$ and $\forall u \in V$.

Definition: Let V be a vector space over a field $(F, +, \cdot)$. A linear transformation $f: V \rightarrow V$ is called a linear operator on V (or linear transformation on V).

Example: Show that the function

$f: R^2 \rightarrow R^2$ defined by

$f(x, y) = (x-y, 3x+y)$ $\forall (x, y) \in R^2$, is a linear transformation on the vector space R^2 over the field $(R, +, \cdot)$.

Solution: $\forall (x_1, y_1), (x_2, y_2) \in R^2$, we have

$$f((x_1, y_1) + (x_2, y_2))$$

$$= f(x_1 + x_2, y_1 + y_2)$$

$$= ((x_1 + x_2) - (y_1 + y_2), 3(x_1 + x_2) + (y_1 + y_2))$$

$$= (x_1 + x_2 - y_1 - y_2, 3x_1 + 3x_2 + y_1 + y_2)$$

$$= (x_1 - y_1 + x_2 - y_2, 3x_1 + y_1 + 3x_2 + y_2)$$

$$= (x_1 - y_1, 3x_1 + y_1) + (x_2 - y_2, 3x_2 + y_2)$$

$$= f(x_1, y_1) + f(x_2, y_2)$$

, and $\forall r \in R$ and $\forall (x, y) \in R^2$, we have

53.

$$\begin{aligned}
 & f(r(x, y)) \\
 &= f(rx, ry) \\
 &= (rx - ry, 3(rx) + ry) \\
 &= (r(x-y), r(3x+y)) \\
 &= r(x-y, 3x+y) \\
 &= r f(x, y)
 \end{aligned}$$

$\therefore f$ is a linear transformation on the vector space R^2 over the field $(R, +, \cdot)$.

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Theorem 11: If V and W be two vector spaces over a field $(F, +, \cdot)$ and

$f: V \rightarrow W$ is a linear transformation from V to W , then

i) $f(O_V) = O_W$

ii) $f(-v) = -f(v) \quad \forall v \in V$.

Definition: If V and W be two vector spaces over a field $(F, +, \cdot)$ and $f: V \rightarrow W$ is a linear transformation from V to W , then the kernel of f , which is denoted by $\ker f$, is the set of all $v \in V$ satisfying that $f(v) = O_W$, i.e.
 $\ker f = \{v \in V \mid f(v) = O_W\}$.

Definition: If V and W are two vector

54. spaces over a field $(F, +, \cdot)$ and $f: V \rightarrow W$ is a linear transformation from V to W , then the range of f is the set of all $f(v)$, $v \in V$ and will be denoted by Range f , i.e. Range $f = \{f(v) \mid v \in V\}$.

Theorem 12: If V and W are two vector spaces over a field $(F, +, \cdot)$ and $f: V \rightarrow W$ is a linear transformation from V to W , then

- i) The kernel of f is a subspace of V .
- ii) The range of f is a subspace of W .

Example: Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $f(x, y, z) = (x+y, 2z, z)$ $\forall (x, y, z) \in \mathbb{R}^3$ be a linear transformation on the vector space \mathbb{R}^3 over the field $(\mathbb{R}, +, \cdot)$. Find $\ker f$ and Range f .

Solution:

$$(x, y, z) \in \ker f$$

$$\Rightarrow f(x, y, z) = (0, 0, 0)$$

$$\Rightarrow (x+y, 2z, z) = (0, 0, 0)$$

$$\Rightarrow x+y=0 \text{ and } 2z=0$$

$$\Rightarrow y=-x \text{ and } z=0$$

$$\text{Thus } \ker f = \{(x, -x, 0) \mid x \in \mathbb{R}\}.$$

$$\text{Range } f = \{f(x, y, z) \mid (x, y, z) \in \mathbb{R}^3\}$$

$$55. = \{ (x+y, 2z, z) \mid x, y, z \in R \}$$

$$= \{ (u, 2z, z) \mid u, z \in R \}.$$

Definition: Let f be a linear transformation on a vector space V over a field $(F, +, \cdot)$ and suppose $B = \{v_1, v_2, \dots, v_n\}$ is a basis of V , and let f defined on the elements of B as follows:

$$f(v_1) = k_{11} v_1 + k_{12} v_2 + \dots + k_{1n} v_n$$

$$f(v_2) = k_{21} v_1 + k_{22} v_2 + \dots + k_{2n} v_n$$

$$\vdots$$

$$f(v_n) = k_{n1} v_1 + k_{n2} v_2 + \dots + k_{nn} v_n$$

Then the matrix

$$\begin{pmatrix} k_{11} & k_{12} & \cdots & k_{1n} \\ k_{21} & k_{22} & \cdots & k_{2n} \\ \vdots & \vdots & & \vdots \\ k_{n1} & k_{n2} & \cdots & k_{nn} \end{pmatrix}$$

which is denoted by $m_B(f)$ or $[f]_B$ is called the matrix representation of f relative to the basis B .

Remark: Let B be a basis of a vector space V over a field $(F, +, \cdot)$. Then any vector $v \in V$ can be written uniquely in the form $v = k_1 v_1 + k_2 v_2 + \dots + k_n v_n$ where $B = \{v_1, v_2, \dots, v_n\}$

56. and the coordinate vector of v relative to the basis B is denoted and defined by

$$[v]_B = \begin{pmatrix} k_1 \\ k_2 \\ \vdots \\ k_n \end{pmatrix} = (k_1, k_2, \dots, k_n)^T$$

Example 1: Let $g: R^2 \rightarrow R^2$ defined by $g(x, y) = (x-y, 3x+y)$ $\forall (x, y) \in R^2$ be a linear operator on the vector space R^2 over the field $(R, +, \cdot)$. Find the

representation matrices $m_B(g)$ and $m_S(g)$ of the linear operator g relative to each of the bases $B = \{u_1, u_2\}$ and $S = \{e_1, e_2\}$ for R^2 , where $u_1 = (1, 1)$, $u_2 = (-1, 0)$, $e_1 = (1, 0)$, $e_2 = (0, 1)$.

Solution:

$\forall (a, b) \in R^2$, we have

$$\begin{pmatrix} a \\ b \end{pmatrix} = k_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + k_2 \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} k_1 \\ k_2 \end{pmatrix} + \begin{pmatrix} -k_2 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} k_1 - k_2 \\ k_2 \end{pmatrix}$$

$$\Rightarrow \begin{aligned} k_1 - k_2 &= a \\ k_2 &= b \end{aligned}$$

Thus $k_1 = b$ and $k_2 = b - a$

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57.

$$\text{Hence } (a, b) = bu_1 + (b-a)u_2$$

$$\text{Therefore } [(a, b)]_B = \begin{pmatrix} b \\ b-a \end{pmatrix}$$

$$g(u_1) = g(1, 1) = (1-1, 3+1) = (0, 4)$$

$$= 4u_1 + (4-0)u_2 = 4u_1 + 4u_2 \quad \text{and}$$

$$g(u_2) = g(-1, 0) = (-1-0, -3+0) = (-1, -3)$$

$$= -3u_1 + (-3-(-1))u_2 = -3u_1 - 2u_2$$

$$\text{Therefore } [g]_B = m_B(g) = \begin{pmatrix} 4 & -3 \\ 4 & -2 \end{pmatrix}.$$

Now $\forall (a, b) \in \mathbb{R}^2$, we have

$$g(e_1) = g(1, 0) = (1-0, 3+0) = (1, 3) = 1 \cdot e_1 + 3e_2$$

$$\text{and } g(e_2) = g(0, 1) = (0-1, 0+1) = (-1, 1) = -e_1 + e_2.$$

$$\text{Therefore } [g]_S = m_S(g) = \begin{pmatrix} 1 & -1 \\ 3 & 1 \end{pmatrix}.$$

Example 2: Let V be a vector space over a field $(F, +, \cdot)$, and let $B = \{2, t, e^{2t}, te^{2t}\}$ be a basis of V and let d be the differential operator on V , i.e. $d(v) = \frac{dv}{dt}$. Find the representation matrix of d relative to the basis B .

Solution:

$$d(2) = 0 = 0 \cdot 2 + 0 \cdot t + 0 \cdot e^{2t} + 0 \cdot te^{2t}$$

$$d(t) = 1 = 1 \cdot 2 + 0 \cdot t + 0 \cdot e^{2t} + 0 \cdot te^{2t}$$

$$d(e^{2t}) = 2e^{2t} = 0 \cdot 2 + 0 \cdot t + 2 \cdot e^{2t} + 0 \cdot te^{2t}$$

$$d(te^{2t}) = e^{2t} + 2te^{2t} = 0 \cdot 2 + 0 \cdot t + 1 \cdot e^{2t} + 2 \cdot te^{2t}$$

58. Thus $[d]_B = \begin{pmatrix} 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix}$

Ex 13.15)

Theorem 13: Let V be a vector space over a field $(F, +, \cdot)$ and let B be a basis for V and let f_1 and f_2 be any linear operators on V and $k \in F$, then we have

i) $m_B(f_1 + f_2) = m_B(f_1) + m_B(f_2)$ that is.

$$[f_1 + f_2]_B = [f_1]_B + [f_2]_B$$

ii) $m_B(kf_1) = k m_B(f_1)$ that is $[kf_1]_B = k[f_1]_B$

iii) $m_B(f_1 \circ f_2) = m_B(f_1) \cdot m_B(f_2)$ that is

$$[f_1 \circ f_2]_B = [f_1]_B \cdot [f_2]_B$$

Example: Let V be a vector space over a field $(F, +, \cdot)$ and let $B = \{e^{5t}, te^{5t}\}$ and let d and h be two linear operators on V defined by $d(v) = 3 \frac{dv}{dt} v \quad \forall v \in V$ and $h(e^{5t}) = 3e^{5t} + te^{5t} \frac{dt}{dt}$ and $h(te^{5t}) = e^{5t} - te^{5t}$. Find $m_B(d+3h)$ and $m_B(doh)$.

Solution:

$$\begin{aligned} d(e^{5t}) &= 3 \frac{d}{dt} e^{5t} = 3(5e^{5t}) = 15e^{5t} \\ &= 15e^{5t} + 0 \cdot te^{5t}. \end{aligned}$$

$$\begin{aligned} d(te^{5t}) &= 3 \frac{d}{dt}(te^{5t}) = 3(e^{5t} + 5te^{5t}) \\ &= 3e^{5t} + 15te^{5t}. \end{aligned}$$

59. Thus $m_B(d) = \begin{pmatrix} 15 & 3 \\ 0 & 15 \end{pmatrix}$

$$h(e^{5t}) = 3e^{5t} + te^{5t}$$

$$h(te^{5t}) = e^{5t} - te^{5t}$$

Thus $m_B(h) = \begin{pmatrix} 3 & 1 \\ 1 & -1 \end{pmatrix}$.

By theorem 13, $m_B(d+3h) = m_B(d) + m_B(3h)$

$$= m_B(d) + 3m_B(h) = \begin{pmatrix} 15 & 3 \\ 0 & 15 \end{pmatrix} + 3 \begin{pmatrix} 3 & 1 \\ 1 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} 15 & 3 \\ 0 & 15 \end{pmatrix} + \begin{pmatrix} 9 & 3 \\ 3 & -3 \end{pmatrix} = \begin{pmatrix} 24 & 6 \\ 3 & 12 \end{pmatrix}, \text{ and}$$

$$m_B(d \circ h) = m_B(d) \cdot m_B(h)$$

$$= \begin{pmatrix} 15 & 3 \\ 0 & 15 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 48 & 12 \\ 15 & -15 \end{pmatrix}$$