

### Lecture 3: Full Derivation of the Rotating Coordinates

Q By Using the total derivative of a vector in a rotating system relationship, derive the equation of momentum in the dynamic meteorology.

Sol

$$\underbrace{\frac{d\vec{A}}{dt}}_{\text{absolute system}} = \underbrace{\frac{d\vec{A}}{dt}}_{\text{rotational system}} + \vec{\Omega} \times \vec{A} \quad \dots (1) \quad \text{Total Der. of a vector in a Rot. Sys.}$$

$$\frac{d\vec{V}_a}{dt} = \sum \vec{F} \quad \dots (2) \quad \text{Newton's 2nd law of motion in an absolute reference}$$

Now, Apply eqn 1 to a position vector ( $\vec{r}$ )

$$\frac{d\vec{r}}{dt} = \frac{d\vec{r}}{dt} + \vec{\Omega} \times \vec{r} \quad \dots (3)$$

$$\therefore \vec{V}_a = \underbrace{\vec{V}}_{\text{relative to coord.}} + \underbrace{\vec{\Omega} \times \vec{r}}_{\text{velocity of the coord. itself}} \quad \dots (4)$$

Now Apply eqn 1 to the velocity vector  $\vec{V}_a$

$$\left(\frac{d\vec{V}_a}{dt}\right) = \left(\frac{d\vec{V}_a}{dt}\right) + \vec{\Omega} \times \vec{V}_a \quad \dots (5)$$

Substitute eqn 4 in eqn 5,

$$\begin{aligned} \left(\frac{d\vec{V}_a}{dt}\right) &= \frac{d}{dt} [\vec{V} + \vec{\Omega} \times \vec{r}] + \vec{\Omega} \times [\vec{V} + \vec{\Omega} \times \vec{r}] \\ &= \left(\frac{d\vec{V}}{dt}\right) + \frac{d}{dt} (\vec{\Omega} \times \vec{r}) + \vec{\Omega} \times \vec{V} + \vec{\Omega} \times (\vec{\Omega} \times \vec{r}) \\ &= \left(\frac{d\vec{V}}{dt}\right) + \underbrace{\left(\frac{d\vec{\Omega}}{dt} \times \vec{r}\right)}_{=0 \text{ (why?)}} + \left(\vec{\Omega} \times \frac{d\vec{r}}{dt}\right) + \vec{\Omega} \times \vec{V} \\ &\quad + \vec{\Omega} \times (\vec{\Omega} \times \vec{r}) \end{aligned}$$

$$\therefore \left(\frac{d\vec{V}_a}{dt}\right) = \left(\frac{d\vec{V}}{dt}\right) + \left(\vec{\Omega} \times \frac{d\vec{r}}{dt}\right) + \vec{\Omega} \times \vec{V} + \vec{\Omega} \times (\vec{\Omega} \times \vec{r})$$

Thus

$$= \left(\frac{d\vec{V}}{dt}\right) + 2(\vec{\Omega} \times \vec{V}) + \vec{\Omega} \times (\vec{\Omega} \times \vec{r})$$

(1)

To be continued... 1



By using a vector triple product :

$$\vec{A} \times (\vec{B} \times \vec{C}) = (\vec{A} \cdot \vec{C})\vec{B} - (\vec{A} \cdot \vec{B})\vec{C}$$

Thus 
$$\vec{\Omega} \times (\vec{\Omega} \times \vec{r}) = (\vec{\Omega} \cdot \vec{r})\vec{\Omega} - (\vec{\Omega} \cdot \vec{\Omega})\vec{r}$$
  

$$= -\Omega^2 \vec{R}$$

$$\therefore \left( \frac{d\vec{v}_a}{dt} \right) = \left( \frac{d\vec{v}}{dt} \right) + 2(\vec{\Omega} \times \vec{v}) - \Omega^2 \vec{R} \dots (6)$$

Using eqn 2

$$\therefore \frac{d\vec{v}_a}{dt} = \frac{d\vec{v}}{dt} + 2(\vec{\Omega} \times \vec{v}) - \Omega^2 \vec{R} = \sum \vec{F}$$

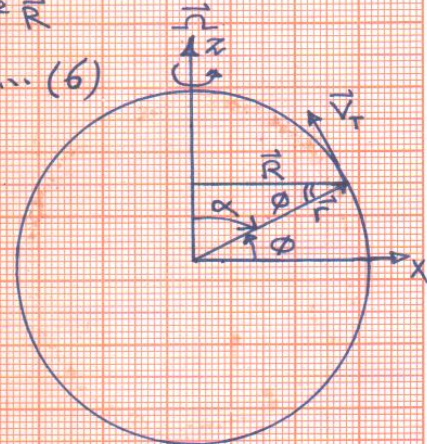
If the only forces acting on the atmosphere are :

1. pgf
2. gravitation
3. Friction

we rewrite Newton's 2nd law with the aid of eqn 6.

$$\frac{d\vec{v}}{dt} = \underbrace{-2\vec{\Omega} \times \vec{v}}_{\text{Coriolis force}} - \underbrace{\frac{1}{\rho} \nabla p}_{\text{pressure gradient force (pgf)}} + \underbrace{\vec{g}}_{\text{gravity}} + \underbrace{\vec{F}_r}_{\text{Frictional force}} \dots (7)$$

centrifugal force  
gravitation



$$|\vec{R}| = |\vec{r}| \cos \phi$$

Tangential velocity  $\vec{V}_T = \vec{\Omega} \times \vec{r}$

$$|\vec{V}_T| = |\vec{\Omega}| R$$
  

$$= |\vec{\Omega}| |\vec{r}| \sin \alpha$$
  

$$= |\vec{\Omega} \times \vec{r}|$$

This form of the momentum equation is the basic to most work in dynamic meteorology.

②